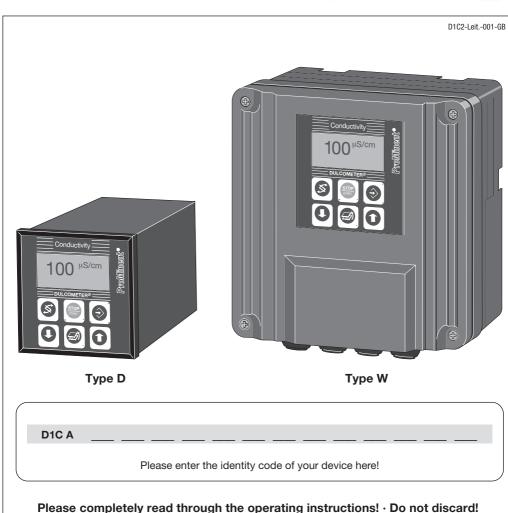
Operating Instructions

DULCOMETER® D1C

Part 2: Adjustment and Operation, Measured Variable Conductive Conductivity





The operator shall be liable for any damage caused by installation or operating errors!

1 Device Identification / Identity Code

D1C A	DULO	COMET	ER® Co	ntroll	er Serie	s D1C	/ Ve	rsior	ı A							
			of mou													
	D				llation 9	6 x 96	mm									
[W	Wall r	nountin													
			Operating voltage 0 230 V 50/60 Hz													
		0														
		1 2														
		3	200 V 50/60 Hz (only with control panel installation) 100 V 50/60 Hz (only with control panel installation)													
		4														
		۲	Measured variable													
					ductivity											
			٦	-			of n	neas	ured	variabl	е					
			- 1 1	1)/4-20 r						
				3								200/20)00 į	ιS/cι	m; 0-20	/200 mS/cm)
						Corr	ectic	n va	riable	е						
					0	None										
					2					minal (F)				
					3					ındard	signal					
			1		4	ivian				entry rd cont	rol					
						0		ne	Ji Wal	u cont	101					
						1			dard	signal (0/4-20	mA				
						2				y 0-500						
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							닉	-	Paus		al outp					
								- 1	0	None		uı				
								_ F	1			nal 0/	4-20) mA	measu	red value
									2							l variable
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										G M					id valve	
										R						r with feedback
										' ii	7 (1011)			ontr		. Will loodston
											0	Non				
											2	Two				
																racteristic
												0		Vone	ortional	control
												2			control	CONTROL
												Ť	Ť			output
														0	None	
																Language
															D	German
															E F	English
															H	French Italian
															N	Dutch
															S	Spanish
															Р	Polish
															Α	Swedish
															В	Portuguese
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	1	\downarrow	\downarrow	1	\downarrow	- ↓	1	,	\downarrow	1	. ↓	- ↓		1	\downarrow	
_	_								_					V		
D1C A					_	_		_			_					
	Places enter the identity code of your device here!															

2 General User Information

		Page
1	Device Identification / Identity Code	2
2	General User Information	3
3	Device Overview / Controls	4
4	Functional Description	5
5	Display Symbols	6
6	Operation diagram	7
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	Overview	
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	Overview	13
	Description	14
9	Fault / Bemarks / Troubleshooting	30

General User Information

These operating instructions describe the technical data and function of the series DULCOMETER® D1C controller, provide detailed safety information and are divided into clear steps.



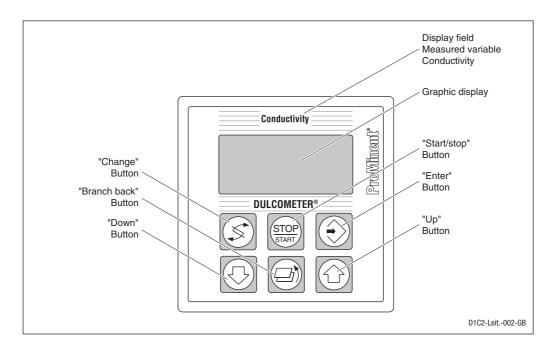
IMPORTANT

- Please observe the parts of these operating instructions applicable to your particular version! This is indicated in the Section "Device Identification / Identity Code"!
- Correct measuring and metering is only possible in the case of impeccable operation of the sensor. The sensor has to be calibrated / checked regularly!

NOTE

A form "Documentation of controller settings type D1C" is available under www.prominent.com/documentation_D1C for the purpose of documenting the controller settings.

3 Device Overview / Controls





CHANGE button

To change over within a menu level and to change from one variable to another within a menu point.



START/STOP button

Start/stop of control and metering function.



FNTFR button

To accept, confirm or save a displayed value or status. For alarm acknowledgement.



UP button

To increase a displayed numerical value and to change variables (flashing display)



BRANCH BACK button

Back to permanent display or to start of relevant setting menu.



DOWN button

To decrease a displayed numerical value and to change variables (flashing display).

4 Functional Description

NOTE

Please refer to the description of the complete operating menu in Section 8 for a detailed description of the individual characteristics of the DULCOMETER® D1C controller!

4.1 Operating Menu

The D1C controller permits settings to be made in two different menus. All values are preset and can be changed in the **complete operating menu**.

The controller is delivered with a **restricted operating menu** so that the D1C controller can be used effectively in many applications from the very onset. If adaptations prove to be necessary, all relevant parameters can then be accessed by switching over to the complete operating menu.

4.2 Access Code

Access to the setting menu can be prevented by setting up an access code. The D1C controller is supplied with the access code 5000 which permits free access to the setting menu. The calibration menu remains freely accessible even if access to the setting menu is blocked by the code.

4.3 Control

The D1C can operate as a proportional controller or as a PID controller - depending on the device version (see identity code) and the setting.

The controlled variable is recalculated once a second. Control procedures which require rapid correction of setpoint deviations (less than approx. 30 seconds) cannot be processed with this controller. The cycle times must be taken into consideration when activating solenoid valves (pulse length) in the same way as their running times when activating servomotors (3-point).

Via the control input pause, the control function (selection of controlled variable) can be switched off. The calculation of the controlled variable starts again after cessation of "pause".

4.4 Feed Forward Control

The D1C controller can process a signal of a feed forward control. Depending on the device version (see identity code) and the setting, this signal can be obtained in any form of a 0–20 mA or 4–20 mA signal or as a digital contact signal with the maximum frequencies 10 Hz or 500 Hz.

This signal can be used, for example, for flow-proportional metering (multiplicative effect) or feed forward-dependent basic load metering (additive effect). The result of control variable calculation from the proportional or PID control is multiplied by or added to the feed forward signal. A multiplicative feed forward variable at the level of the set rated value carries over the calculated control variable unchanged into the controlled variable:

Controlled variable = Feed forward variable/rated value x calculated control variable

During start-up, the zero point has to be checked. The multiplicative feed forward control is not designed for switching off permanently the actuating variable (signal \approx 0).

An additive feed forward variable at the level of the rated value results in maximum controlled variable:

Controlled variable (max. 100 %) = Feed forward variable/rated value x max. controlled variable + calculated control variable

4.5 Error Messages

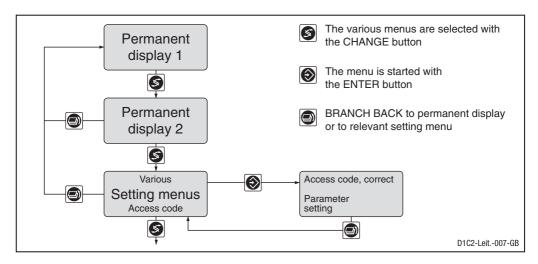
Error messages and information are indicated on the bottom line in the permanent display 1. Errors to be acknowledged (acknowledgement switches off the alarm relay) are indicated by the symbol "E". Errors/notes which still apply after acknowledgement are indicated alternately. Faults which are rectified of their own accord due to changed operating situations are removed from the permanent display without the need for acknowledgement.

5 Display Symbols

The display of the DULCOMETER® D1C controller uses the following symbols:

Description	Comment	Symbol
Limit value transgression Relay 1, upper	Symbol left	1
Relay 1 lower	Symbol left	ļ.
Relay 2 upper	Symbol right	1
Relay 2 lower	Symbol right	ļ.
Metering pump 1 (Increase conductivity) Control off	Symbol left	
Control on	Symbol left	
Metering pump 2 (Reduce conductivity) Control off	Symbol right	
Control on	Symbol right	
Solenoid valve 1 (Increase conductivity) Control off	Symbol left	4
Control on	Symbol left	
Solenoid valve 2 (Reduce conductivity) Control off	Symbol right	L
Control on	Symbol right	
Servomotor Control, open relay		1 L
Control, close relay		
Without control		4
Position feedback	Thickness of bar increases from left to right during opening	-
Stop button pressed		0
Manual metering		M
Fault		3

6 Operation diagram



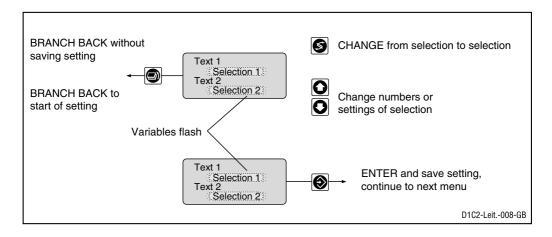
NOTE

Access to the setting menus can be barred with the access code!

The number and scope of setting menus depends on the device version!

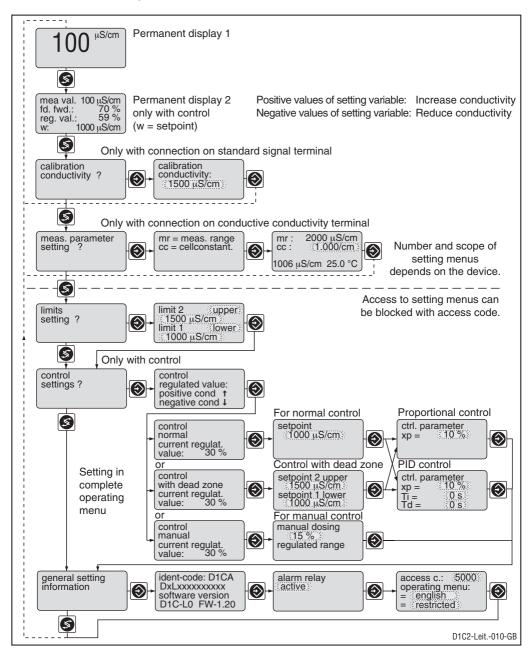
If the access code is selected correctly in a setting menu, the following setting menus are also accessible!

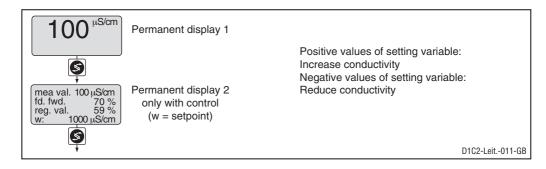
If within a period of 10 minutes no button is pushed, the unit automatically branches back from the calibrating menu or a setting menu to the permanent display 1.



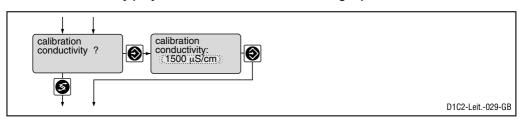
7 Restricted Operating Menu / Overview

The restricted operating menu permits simple operation of the most important parameters. The following overview shows the settings which can be selected:





Calibration conductivity (only for connected terminal standard signal)



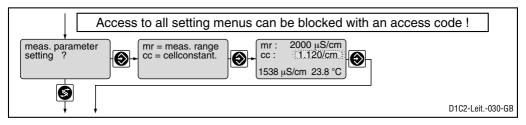
During calibration, the D1C sets the command outputs to "0". Exception: if a basic load or a manual control output were set, these are maintained during calibration. The standard signal outputs mA (measuring value or correction value) are frozen.

The actually measured value will be proposed; this value is adjustable (arrow keys). On successful completion of calibration, all error checks which refer to the measured value are restarted.

		Possible values		
	Initial value	Increment	Lower value	Upper value
Calibration conductivity	measured value	as per measuring range	as per measuring range	as per measuring range

Error message	Condition effect	Remarks
Measured value too low Value > xx mS/cm Check measuring range	Value < 2 % of measuring range	Check measuring range
Measured value too high Value < xx mS/cm Check measuring range	Value > 100 % of measuring range	Check measuring range

Calibration conductivity (only for connected terminal conductive conductivity) Measuring parameter

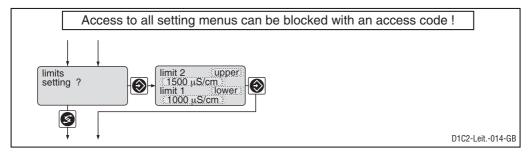


		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Cell constant cc	1.000/cm	0.0001/cm 0.001/cm 0.01/cm	0.0060/cm 0.150/cm 1.50/cm	0.1499/cm 1.499/cm 12.00/cm	cc can be adjusted for all mr over the complete area

The measured value can be adjusted to the actual conductivity value by changing the cell constants (arrow keys).

NOTE
The following menus apply generally!

Limit values

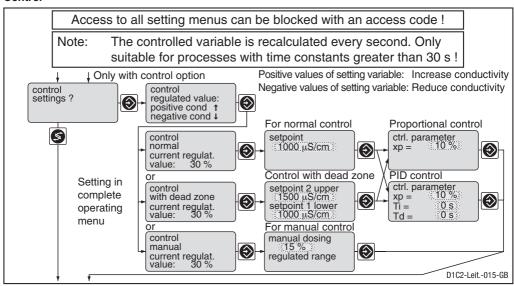


			Possible values			
		Initial value	Increment	Lower value	Upper value	Remarks
Type of limit transgression	Limit 1: Limit 2:	lower upper	lower upper off**			**only with limit value relay
Limit value	Limit 1: Limit 2:	10 μS/cm 15 μS/cm	0.01 μS/cm	-1 μS/cm	21 μS/cm	Measuring range 20 μS/cm
	Limit 1: Limit 2:	25 μS/cm 37.5 μS/cm	0.01 μS/cm	-2.5 μS/cm	52.5 μS/cm	Measuring range 50 μS/cm*
	Limit 1: Limit 2:	100 μS/cm 150 mS/cm	0.1 μS/cm	-10 μS/cm	210 μS/cm	Measuring range 200 μS/cm

		Possible values	 		
	Initial value	Increment	Lower value	Upper value	Remarks
Limit 1:	250 μS/cm	0.1 μS/cm	-25 µS/cm	525 μS/cm	Measuring range 500 μS/cm*
Limit 2:	375 μS/cm				
Limit 1:	1000 μS/cm	1 μS/cm	-100 μS/cm	2100 µS/cm	Measuring range 2000 μS/cm
Limit 2:	1500 μS/cm				
Limit 1:	2500 μS/cm	1 μS/cm	-250 μS/cm	5250 μS/cm	Measuring range 5000 µS/cm*
Limit 2:	3750 μS/cm				
Limit 1:	10 mS/cm	0.01 mS/cm	-1 mS/cm	21 mS/cm	Measuring range 20 mS/cm
Limit 2:	15 mS/cm				
Limit 1:	100 mS/cm	0.1 mS/cm	-10 mS/cm	210 mS/cm	Measuring range 200 mS/cm
Limit 2:	150 mS/cm				
Limit 1:	500 mS/cm	1 mS/cm	-50 mS/cm	1050 mS/cm	Measuring range 1000 mS/cm*
Limit 2:	750 mS/cm				

^{*}only for connected terminal standard signal

Control



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Setpoint	10 μS/cm	0.01 µS/cm	-1 μS/cm	21 µS/cm	Measuring range 20 µS/cm Measuring range 50 µS/cm*
	15 μS/cm 100 μS/cm	0.01 μS/cm 0.1 μS/cm	-2.5 μS/cm -10 μS/cm	52.5 μS/cm 210 μS/cm	Measuring range 200 μS/cm
	250 μS/cm 1000 μS/cm	0.1 μS/cm 1 μS/cm	-25 μS/cm -100 μS/cm	525 μS/cm 2100 μS/cm	Measuring range 500 μS/cm* Measuring range 2000 μS/cm
	2500 µS/cm	1 μS/cm	-250 µS/cm	5250 μS/cm	Measuring range 5000 µS/cm*
	10 mS/cm 100 mS/cm	0.01 mS/cm 0.1 mS/cm	-1 mS/cm -10 mS/cm	21 mS/cm 210 mS/cm	Measuring range 20 mS/cm Measuring range 200 mS/cm
	500 mS/cm	1 mS/cm	-50 mS/cm	1050 mS/cm	Measuring range 1000 mS/cm*

		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
					2 setpoints necessary for control with dead zone. Setpoint 1 < setpoint 2
					Adjustment of measuring range on page 15/18
Control parameter xp Control parameter Ti Control parameter Td Manual metering	10 % off off 0 %	1 % 1 s 1 s 1 %	1 % 1 s 1 s -100 %	500 % 9999 s 2500 s +100 %	xp referred to measuring range Function off = 0 s Function off = 0 s

^{*}only for connected terminal standard signal

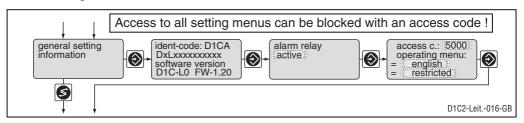
Abbreviations for control variables:

x₂ = 100 %/Kp (inverse proportional coefficient)

T_i = I controller integration time [s]

 $T_d = D$ controller differential time [s]

General settings



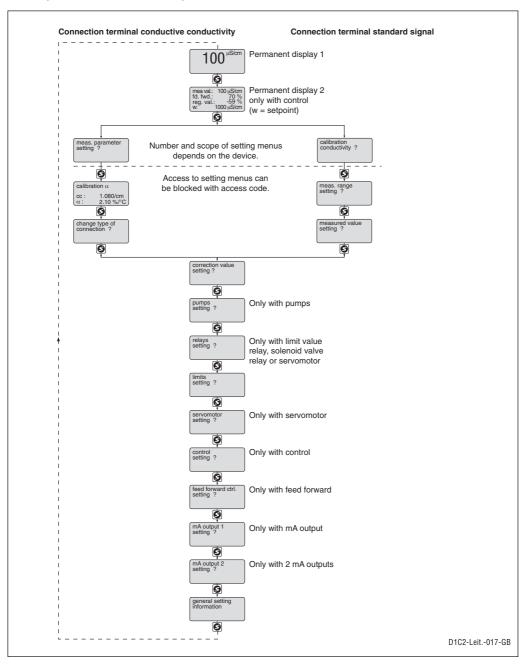
		Possible values	Possible values				
	Initial value	Increment	Lower value	Upper value	Remarks		
Alarm relay	active	active not active					
Access code	5000	1	1	9999			
Language	as per identity code	as per identity code					
Operating menu	restricted	restricted complete					

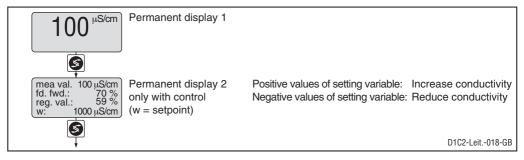
Access Code

Access to the setting menu can be prevented by setting up an access code. The DULCOMETER® D1C controller is supplied with the access code 5000 which permits free access to the setting menu. The calibration menu remains freely accessible even when access to the setting menu is blocked by the code.

8 Complete Operating Menu / Overview

All parameters of the controller can be set in the complete operating menu (access see previous page). The following overview shows the settings which can be selected:

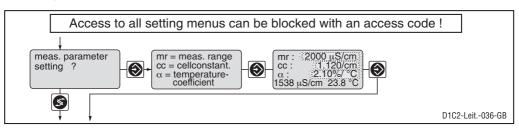




With connection on terminal standard signal see page 18

With connection on terminal conductive conductivity:

Measuring parameter (only for connected terminal conductive conductivity)



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Measuring range mr	02000 μS/cm	020 μS/cm 0200 μS/cm 02000 μS/cm 020 mS/cm 0200 mS/cm			Setpoints and limit values are switched to the corresponding startup values
Cell constant cc	1,000/cm	0.0001/cm 0.001/cm 0.01/cm	0.0060/cm 0.150/cm 1.50/cm	0.1499/cm 1.499/cm 12.00/cm	cc can be adjusted for all mr over the complete area
Temperature coefficient α	1.90 %/°C	0.01 %/°C	0 %/°C	10 %/°C	

The measured value can be adjusted to the actual conductivity value by changing the cell constants (arrow keys). Prerequisite is a known temperature coefficient and a constant temperature.



IMPORTANT

When changing the measuring range, metering and control are stopped, the setpoints, limit values, and the standard signal output are set to the corresponding startup values! Check these settings in all menus!

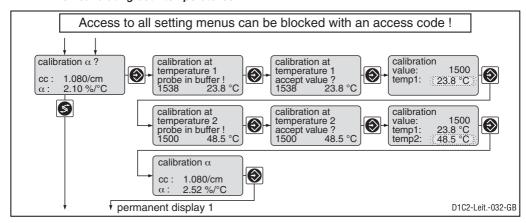
Calibrating temperature coefficient α (only for connected terminal conductive conductivity)

The temperature coefficient α is newly determined by a 2-point calibration. During calibration, the D1C sets the command outputs to "0". Exception: if a basic load or a manual control output were set, these are maintained during calibration. The standard signal outputs mA (measuring value or correction value) are frozen.



ATTENTION

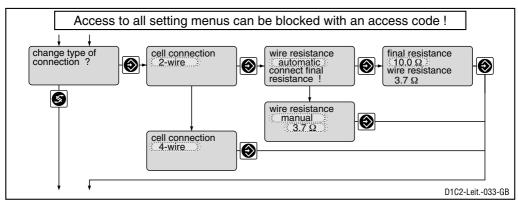
The conductivity values you enter must be based on 25 °C. You must use the same solution when calibrating both temperatures!



		Possible values			
	Initial value	Increment	Lower value	Upper value	Measuring range
Set sensor	Measuring value	0.01 μS/cm 0.1 μS/cm 1 μS/cm 0.01 mS/cm 0.1 mS/cm	-1 μS/cm -10 μS/cm -100 μS/cm -1 mS/cm -10 mS/cm	21 μS/cm 210 μS/cm 2100 μS/cm 21 mS/cm 210 mS/cm	20 μS/cm 200 μS/cm 2000 μS/cm 20 mS/cm 200 mS/cm
Set temperature	Correction value	0.1 °C	0 °C	100 °C	

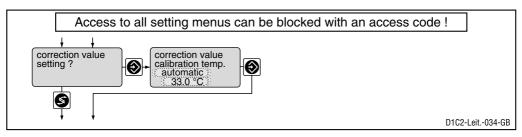
Error message/Warning	Condition	Remarks
Temperature range restricted xx - 100 °C		For the chosen temperature coefficient α , a correct reading can only be obtained for the displayed temperature range.
Temperature distance wrong	Δ temperature \geq 10.0 °C Δ temperature \leq 50.0 °C	

Sensor connection (only for connected terminal conductive conductivity)



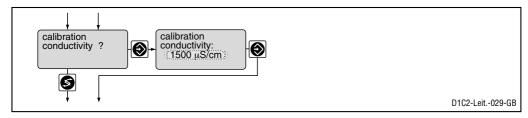
		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Sensor connection	2-wire 4-wire	2-wire			
Determine wire resistance	manual	manual automatic			
Manual entry wire resistance	0.5 Ω	0.1 Ω	0 Ω	50 Ω	
Final resistance	10.0 Ω	0.1 Ω	10 Ω	50 Ω	

Correction value (only for connected terminal conductive conductivity)



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Type of temperature compensation	as per identity code	manual automatic off			
Manual temperature	25 °C	0.1 °C	0 °C	100 °C	
Automatic temperature	Correction value	0.1 °C	0 °C	100 °C	

Calibration conductivity (only for connected terminal standard signal)



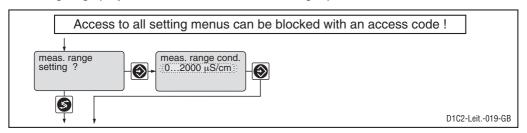
During calibration, the D1C sets the command outputs to "0". Exception: if a basic load or a manual control output were set, these are maintained during calibration. The standard signal outputs mA (measuring value or correction value) are frozen.

The actually measured value will be proposed; this value is adjustable (arrow keys). On successful completion of calibration, all error checks which refer to the measured value are restarted.

		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Calibration conductivity	Measured value	depending on measuring range	depending on measuring range	depending on measuring range	

Error message	Error message Condition effect	
Measured value too low value > xx mS/cm Check measuring range	Value < 2 % of measuring range	Check measuring range
Measured value too high value < xx mS/cm Check measuring range	Value > 100 % of measuring range	Check measuring range

Measuring range (only for connected terminal standard signal)



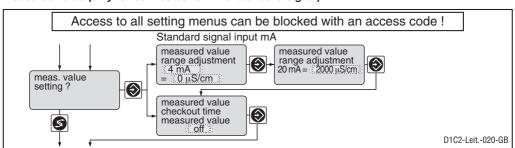


IMPORTANT

When changing the measuring range, setpoints and limit values are switched over to their respective initial values. The settings must be checked in all menus!

		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Measuring range	02000 μS/cm	01000 mS/cm* 020 mS/cm 020 mS/cm 05000 μS/cm* 0500 μS/cm* 0500 μS/cm 0500 μS/cm 0500 μS/cm 050 μS/cm			Setpoints and limit values are switched over to their respective initial values *only with connection on standard signal

Measured value (only for connected terminal standard signal)





IMPORTANT

When changing the range adjustment, the adjustments in all menus have to be checked!

	lmiki al valva	Possible values	Lawarualua	l Hanna valva	Demonto
	Initial value	Increment	Lower value	Upper value	Remarks
Standard signal input lower signal limit	4 mA	0 mA 4 mA			
Allocated special voltage	0–2000 μS/cm	depending on measuring range	-5 % of final value	+5 % of final value	
Checkout time	off	1 s	1 s	9999 s	Constant measurement signal results in message and alarm. Function off = 0 s

Control time measuring value



IMPORTANT

This function may not be activated for applications where it can be assumed that the measuring value does not change.

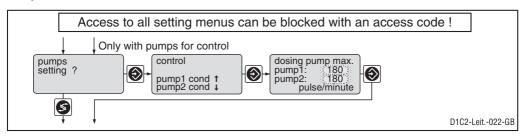
This function checks whether the measuring value from the sensor (measuring value input) changes within the "control time measuring value". It is assumed that the value does not change for an intact sensor.

If the measuring value does not change during this control time, the DULCOMETER® D1C sets the control output to "0" and the alarm relay drops out. The LCD display shows e.g. the message "check mS-probe".

NOTE

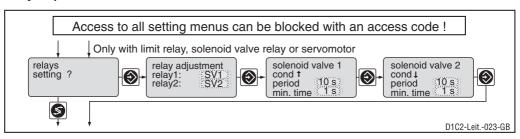
The following menus apply generally.

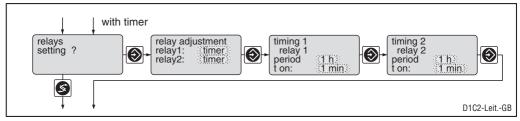
Pumps



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Max. stroke/minute of pumps 1 and 2	180	1	1	500	off = 0 strokes/min

Relay for power control

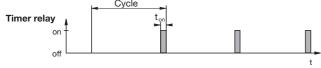




		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Relay adjustment	as per identity code				
Relay 1		Solenoid valve 1 Limit value 1* Actuator 1 Timer 1 Servomotor off			*For "limit value", the relays remain active, even in the event of a fault.
Relay 2		Solenoid valve 2 Limit value 2* Actuator 2 Timer 2 off			
Cycle	10 s	1 s	10 s	9999 s	for solenoid valve
min. time	1 s	1 s	1 s	Cycle/2	for solenoid valve Set here the smallest permitted operating factor of the connected device.
Period (Cycle)	off	1 h	1 h / off	240 h	for timer
t on	1 min	1 min	1 min	60 min	for timer

NOTE

The limit value relay can be defined in such a way as to respond as a control element, i.e. if a limit value relay closes a circuit, it opens when a pause contact is activated and/or for a subsequent delay period t_a (if t_a is set to > 0 min in "General settings").





IMPORTANT

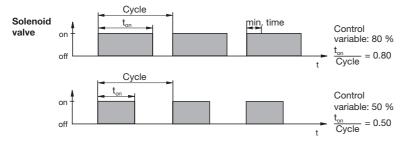
The timer will be reset if there is a drop in the power supply.

At the end of the (timer) cycle time, the DULCOMETER® D1C closes the assigned relay for the duration of "t on" (timer). "Pause" interrupts the timer.

When the clock is shown in the LC display, the timer can be reset to the start of the cycle at precisely this point using the enter button.

The % figure in the LC display indicates the progress of the current cycle.

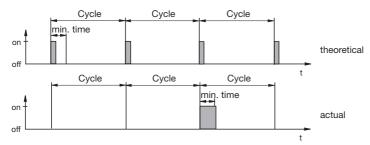
Timer relays may be used, e.g. for shock metering or sensor cleaning.



The switching time of the DULCOMETER® D1C (solenoid valve) depends on the actuating variable and the "min. time" (smallest permitted operating factor of the connected device).

The actuating variable determines the ratio t_{or}/cycle and thus the switching times (see fig. above). The "min. time" influences the switching times in two situations:

a) theoretical switching time < min. time:

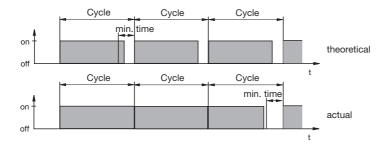


The DULCOMETER® D1C does not switch for a certain number of cycles until the sum of the theoretical switching times exceeds the "min. time". Then the DULCOMETER® D1C switches for the duration of this total time.

b) theoretical switching time > (cycle - min. time)

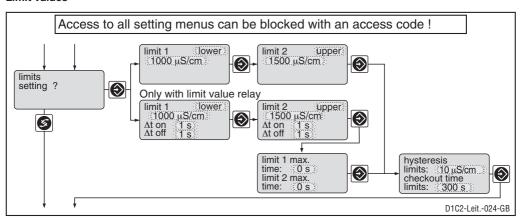
and

calculated switching time < cycle



The DULCOMETER® D1C does not deactivate for a certain number of cycles until the differences between cycle and theoretical switching time exceed the "min. time".

Limit values



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Type of limit Limit 1: transgression Limit 2:	lower upper	upper lower off*			Limit transgression when exceeding or dropping below value *only with limit value relay
Limit value 1 Limit value 2	500; 750 mS/cm 100; 150 mS/cm 10; 15 mS/cm 2500; 3750 μS/cm 1000; 1500 μS/cm 250; 375 μS/cm 100; 150 μS/cm 25; 37 μS/cm 10; 15 μS/cm	1 mS/cm 0.1 mS/cm 0.01 mS/cm 1 μS/cm 1 μS/cm 0.1 μS/cm 0.1 μS/cm 0.1 μS/cm	-50 mS/cm -10 mS/cm -1 mS/cm -250 μS/cm -100 μS/cm -25 μS/cm -10 μS/cm -1 μS/cm -1 μS/cm	1050 mS/cm 210 mS/cm 21 mS/cm 5250 μS/cm 2100 μS/cm 525 μS/cm 210 μS/cm 52.5 μS/cm 21 μS/cm	Meas. range 1000 mS/cm** Meas. range 200 mS/cm Meas. range 20 mS/cm Meas. range 5000 μS/cm** Meas. range 2000 μS/cm** Meas. range 500 μS/cm** Meas. range 200 μS/cm Meas. range 200 μS/cm Meas. range 20 μS/cm** Meas. range 20 μS/cm**
Hysteresis limits	5 mS/cm** 1 mS/cm 0.1 mS/cm 25 μS/cm** 10 μS/cm 2.5 μS/cm** 1.0 μS/cm 0.25 μS/cm**	1 mS/cm 0.1 mS/cm 0.01 mS/cm 1 μS/cm 1 μS/cm 0.1 μS/cm 0.1 μS/cm 0.1 μS/cm 0.01 μS/cm	-2 mS/cm -0.4 mS/cm -0.04 mS/cm -10 μS/cm -4 μS/cm -1 μS/cm -0.4 μS/cm -0.1 μS/cm -0.04 μS/cm	1050 mS/cm 210 mS/cm 21 mS/cm 5250 μS/cm 2100 μS/cm 525 μS/cm 210 μS/cm 52.5 μS/cm 21 μS/cm	Effective in direction of "cancelling limit transgression"
Checkout time limits	off	1 s	1 s/off	9999 s	Result in message and alarm. off = 0 s: Function switched off, no message, no alarm

		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Controlling	on	on off			
Actuating direction limit value 1; limit value 2	active closed	active closed active open			Reacts as make contact Reacts as break contact
Switch-on delay ∆t on	0 s	1 s	0 s	9999 s	
Switch-off delay ∆t off	0 s	1 s	0 s	9999 s	

^{**}only for connected terminal connection on standard signal

If the limit is exceeded for longer than the "Delay time - limit values", an error message is given which must be acknowledged, and the alarm relay circuit is broken. If "Controller" is also set to "off" the control process stops.

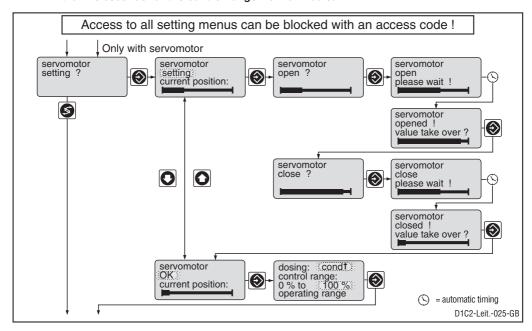
Servomotor

The **operating range** is defined by the total resistance range of the feedback potentiometer. The maximum limit of the range actually used is set by defining the **control range**.



ATTENTION

- Activation of the servomotor must be carried out with the same meticulous care as taken when calibrating a measuring sensor.
- To ensure correct operation, the activation time of the actuator used should not be less than 25 seconds for the control range from 0...100 %!

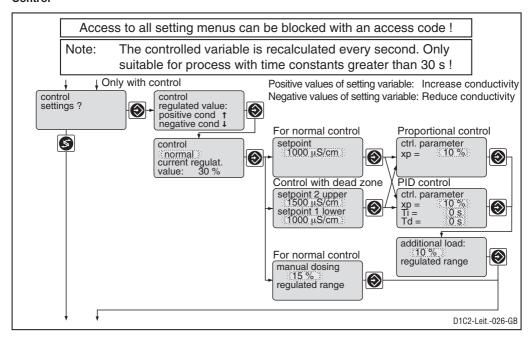


		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Servomotor	Setting	Setting ok off			
Control direction	cond. ↑	cond. ↑ cond. ↓			
Control range	100 %	1 %	10 %	100 %	in % of operating range

NOTE

- If the broad bar is to the far right, the stroke adjustment motor is fully open.
- The continuous display shows the degree in % to which it is open (the greater the
 percentage, the more open the stroke adjustment motor).

Control



		Possible values	i			
	Initial value	Increment	Lower value	Upper value	Remarks	
Control	normal	normal with dead zone manual			When controlling with dead zone, the feed forward control is not used for measured values within the dead zone	
Setpoint setting	500 mS/cm 100 mS/cm 10 mS/cm 2500 μS/cm 1000 μS/cm 250 μS/cm 100 μS/cm 15 μS/cm 10 μS/cm	1 mS/cm 0.1 mS/cm 0.01 mS/cm 1 μS/cm 1 μS/cm 0.1 μS/cm 0.1 μS/cm 0.1 μS/cm 0.01 μS/cm	-50 mS/cm -10 mS/cm -1 mS/cm -250 μS/cm -100 μS/cm -25 μS/cm -25 μS/cm -10 μS/cm -2.5 μS/cm -1 μS/cm	1050 mS/cm 210 mS/cm 21 mS/cm 5250 μS/cm 2100 μS/cm 525 μS/cm 210 μS/cm 52.5 μS/cm 21 μS/cm	Meas. range 1000 mS/cm* Meas. range 200 mS/cm Meas. range 20 mS/cm Meas. range 5000 μS/cm* Meas. range 2000 μS/cm* Meas. range 5000 μS/cm* Meas. range 2000 μS/cm* Meas. range 200 μS/cm* Meas. range 20 μS/cm* Setpoint 2 ≥ setpoint 1	
Control parameter xp	10 %	1 %	1 %	500 %	xp referred to measuring range	
Control parameter Ti	off	1 s	1 s	9999 s	Function off = 0 s	
Control parameter Td off		1 s	1 s	2500 s	Function off = 0 s	
Additional load 0 %		1 %	-100 %	+100 %		
Manual metering	0 %	1 %	-100 %	+100 %		

^{*}only with connection on terminal standard signal

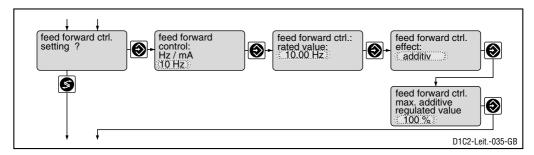
Abbreviations for control variables:

 $x_D = 100 \%/Kp$ (inverse proportional coefficient)

 $T_i^p = I$ controller integration time [s]

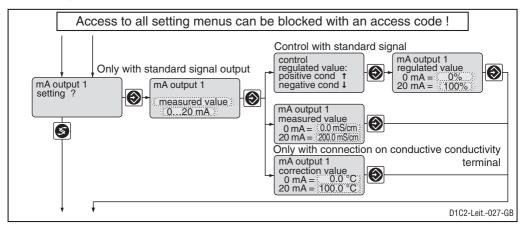
 T_d = D controller differential time [s]

Feed forward control

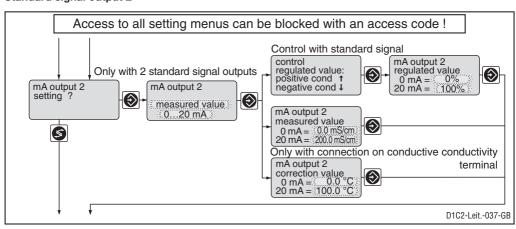


	Initial value	Increment	Lower value	Upper value	Remarks
Feed forward control (Flow)	as per identity code	None 10 Hz 500 Hz			Signal processing: Signal <0.02 Hz = no flow Signal <0.2 Hz = no flow
	with standard signal: 4–20 mA	020 mA 420 mA			Signal <0.2 mA = no flow Signal <4.2 mA = no flow
Feed forward control rated value	10 Hz 500 Hz 20 mA	0.01 Hz 1 Hz 0.01 mA	0.1 Hz 5 Hz 0/4 mA	10 Hz 500 Hz 20 mA	Dependent on signal type. Maximum limitation of range used.
Feed forward control effect	multiplicative	multiplicative additive			
Max. add. regulated value	100 %	1 %	-500 %	+500 %	Only with additive feed forward control

Standard signal output 1



Standard signal output 2

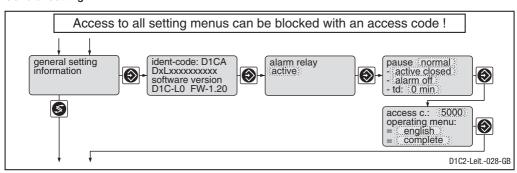


		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Variable allocation	as per identity code	Measured value Controlled variable Correction value			If control applicable Only with correction variable
Output range	020 mA	020 mA 420 mA 3.6/4-20 mA			Reduction to 3.6 mA when alarm relay switches (not limit-value violation)

		Possible values	1		
	Initial value	Increment	Lower value	Upper value	Remarks
Range measured value	0–20 μS/cm 0–50 μS/cm 0–200 μS/cm 0–500 μS/cm 0–5000 μS/cm 0–5000 μS/cm 0–20 mS/cm 0–200 mS/cm 0–1000 mS/cm	0.01 µS/cm 0.01 µS/cm 0.1 µS/cm 0.1 µS/cm 1 µS/cm 0.01 mS/cm 0.1 mS/cm	-1 μS/cm -2.5 μS/cm -10 μS/cm -25 μS/cm -100 μS/cm -250 μS/cm -1 mS/cm -10 mS/cm -50 mS/cm	21 μS/cm 52.5 μS/cm 210 μS/cm 525 μS/cm 2100 μS/cm 5250 μS/cm 21 mS/cm 210 mS/cm	Meas. range 20 μS/cm Meas. range 50 μS/cm* Meas. range 200 μS/cm* Meas. range 500 μS/cm* Meas. range 2000 μS/cm* Meas. range 2000 μS/cm* Meas. range 20 mS/cm Meas. range 200 mS/cm Meas. range 1000 mS/cm*
Range controlled variable	0 %+100 %	1 %	-100 %	+100 %	Minimum range 1 %
Range correction value	0100 °C	0.1 °C	0.0 °C	100 °C	Minimum range 1 °C

^{*}only with connection on standard signal

General setting



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Alarm relay	active	active not active			
Pause	normal	normal hold			
Control input pause	active closed	active closed active open			Reacts as make contact Reacts as break contact
Alarm pause	off	off on			Alarm relay can be triggered by pause contact
td	0 min	1 min	0 min	60 min	
Access code	5000	1	1	9999	
Language	as per identity code	as per identity code			
Operating menu	complete	restricted complete			

Pause Normal

If the pause switch is off, the DULCOMETER® D1C sets the operating outputs to "0" for as long as the pause switch is off or for a set time delay t_d (if t_d is set to > 0 min). Whilst the pause switch is off, the D1C establishes the P-proportion in the background.

With PID-control (identity code characteristics "control characteristic" = 2): the I-proportion is stored when the pause is switched off (I-proportion then usually only present if Tn > 0 has been selected in the "Control setting?" setting menu).

Exception: the standard signal outputs mA for the measured value or correction value are not affected by the pause.

After pause is activated, the operating outputs remain at "0" for the length of the time delay $t_{\rm d}$. The time delay $t_{\rm d}$ must be set up in such a way that in this time e.g. sample water (process-specific current concentration) flows to the sensor.

With PID-control (identity code characteristics "control characteristic" = 2): The control variable output resulting from the pause and the expiry of the time delay t_d is reconciled jointly with the current P-component and (if Tn is set > 0) with the stored I-component.

Pause hold

If the pause switch is off, the DULCOMETER® D1C freezes the operating output at the most recent value for as long as the pause switch is off or for a set time delay t_a (if t_a is set to > 0 min). Whilst the pause switch is off, the D1C establishes the P-proportion in the background.

With PID-control (identity code characteristics "control characteristic" = 2):

Even the mA standard signal outputs for measured value or correction value are frozen.

After pause is activated, the operating outputs remain frozen for the length of the time delay t_d . The time delay t_d must be set up in such a way that in this time e.g. sample water (process-specific current concentration) flows to the sensor.

With PID-control (identity code characteristics "control characteristic" = 2): The control variable output resulting from the pause and the expiry of the time delay t_d is reconciled jointly with the current P-proportion and (if Tn is set > 0) with the newly established I-proportion.

Access Code

Access to the setting menu can be prevented by setting up an access code. The DULCOMETER® D1C controller is supplied with the access code 5000 which permits free access to the setting menu. The calibration menu remains freely accessible even when access to the setting menu is blocked by the code.

Fault / Remarks / Troubleshooting 9

Upper position <40 % max. value Lower position >30 % range	During servomotor setting Position feedback wrong	Calibration* Calibration with error	Stop button		Pause contact	Operation	Electronics error	Servomotor Position not reached	Control "off"	Limit value violation after checkout time limits Control "on"	Feed forward control Signal exceeds/drops below value* Signal drops below multiplicative	upper limit temperature exceeded	Correction measured variable Signal exceeds/drops below value*	Checkout time meas. value exceeded*	Measured value Signal exceeds/drops below value*	Fault
→ ±!	Direction check	Check meas. range	Stop	Pause/Hold	Pause	Note text	System error	Servomotor defective		mS-limit 1 ↑↓ mS-limit 2 ↑↓	Check feed forward input	te-limit †	Check te-input	Check mS-probe	mS-meas. range ↑↓ Check mS-input	Fault text
		m	М О	m	۳ 0	Symbol	м О	m	m∩	n	m m		M	m	mm	Symbol
		Basic load	Stop		Stop	Effect On metering 0	Stop		Stop or basic load			Basic load	Basic load	Basic load	Basic load Basic load	Effect On metering 0
		Stop	Stop	PI part frozen	Stop	ect On control	Stop		Stop		Stop	Stop	Stop	Stop	Stop Stop	ect On control
		ı	No		No/Yes**	Alarm with acknowledgement	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes Yes	Alarm with acknowledgement
adjustment the last valid values are still used	Without correct	ı	Relay drops out	ואס ומומוטו וממונ טווסטוג	No further fault check	Remarks	Electronic data defective	Servomotor closes		Function detachable	Signal <3.0 ±0.2 mA or >23 ±0.2 mA Value last valid is used	α ≥ 4 %/°C	Signal <3.0 ±0.2 mA	Function detachable	Measured value out of measuring range. Signal <3.0 ±0.2 mA or >23 ±0.2 mA	Remarks
potentiometer Adjust the operation region of the servomotor correctly	Check connection of relay,	Repeat calibration Check sensor/buffer	ı		ı	Remedy	Call in service	Check servomotor		Define cause, reset values if necessary	Check sensor, transducer and cable connection		Check sensor, transducer and cable connection	Check function of sensor, Extend checkout time	Check range adjustment Check sensor, transducer and cable connection	Remedy

^{*} only with connection on standard signal **Depends on whether "alarm off" or "alarm on" in "General Settings".