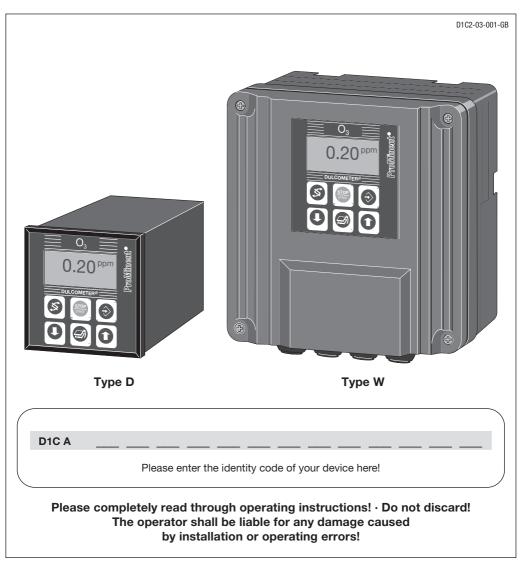
Operating Instructions DULCOMETER[®] D1C

Part 2: Adjustment and Operation, Measured Variable Ozone







1 Device Identification / Identity Code

D1C A	DULO	COMET	ER® Co	ontro	ller S	eries	D1C	/ Ver	sion	A							
	D		Type of mounting Control panel installation 96 x 96 mm														
	W		all mounting														
	Ť				volta	ae											
		0		Operating voltage 230 V 50/60 Hz													
		1	115 V														
		2	200 V			only v	vith p	banel	insta	Ilatic	n)						
		3	100 V	50/6	0 Hz	only v	vith p	anel	insta	Ilatic	n)						
		4	24 V /								,						
		<u> </u>		Mea	asure	d vari	able										
			Z	Ozc	one												
					C	onnec	tion	of m	eası	red	variabl	е					
				1	Te	ermina	ıl, sta	Indar	d sig	nal 0	/4-20 m	۱A					
								ectio	n var	iable)						
							None										
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							0			rwar	d contr	ol					
						$ \vdash$	0	Nor		dowe	signal (1/4 00	m ^				
							2				/ 0-500		mA				
							2				/ 0-300 / 0-10 F						
							Ť	via			rol inpu						
								0	_	lone	or mpe			_			
								1		ause)						
								-				I outp	ut				
										0	none						
										1	Stand	lard si	gnal ()/4-	20 m	A meas	sured value
										2							ol variable
										3							ction variable
										4	2 star					nA out	puts, free programmable
													er co				
											G						mer relays
											M						ve relays
											R	Alarr			cont		or with feedback
												0	No		con	roi	
												2	-		umps		
												L-f-					aracteristic
													0		Non		
													1	_			al control
													2		PID	control	
																Log	output
															0	Nor	
																	Language
																D	German
																E	English
																F	French
																	Italian
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																S P	Spanish Polish
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D1C A																	
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Please enter the identity code of your device here!

2 General User Information

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General User Information

These operating instructions describe the technical data and function of the series D1C DULCOMETER[®] controller, provide detailed safety information and are divided into clear steps.



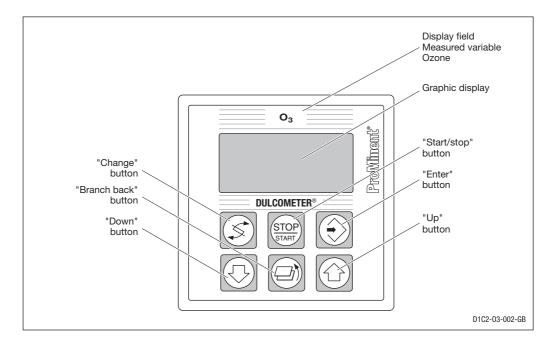
IMPORTANT

- Please observe the parts of these operating instructions applicable to your particular version! This is indicated in the Section "Device Identification / Identity Code"!
- Correct measuring and dosing is only possible in the case of impeccable operation of the probe. The probe has to be calibrated / checked regularly!

NOTE

A form "Documentation of controller settings Type D1C" is available under www.prominent.com/documentation_D1C for purpose of documenting the controller settings.

3 Device Overview / Controls



Ś	CHANGE button To change over within a menu level and to change from one variable to another within a menu point.		UP button To increase a displayed numerical value and to change variables (flashing display)
STOP	START/STOP button Start/stop of control and metering function.		BRANCH BACK button Back to permanent display or to start of relevant setting menu.
	ENTER button To accept, confirm or save a displayed value or status. For alarm acknow- ledgement.	\bigcirc	DOWN button To decrease a displayed numerical value and to change variables (flashing display).

Functional Description 4

NOTE

Please refer to the description of the complete operating menu in Section 8 for a detailed description of the individual characteristics of the D1C controller!

4.1 **Operating Menu**

The DULCOMETER® D1C controller permits settings to be made in two different menus. All values are preset and can be changed in the complete operating menu.

The controller is delivered with a restricted operating menu so that the D1C controller can be used effectively in many applications from the very onset. If adaptations prove to be necessary, all relevant parameters can then be accessed by switching over to the complete operating menu (see "General settings").

4.2 Access Code

Access to the setting menu can be prevented by setting up an access code. The DULCOMETER® D1C controller is supplied with the access code 5000 which permits free access to the setting menu. The calibration menu remains freely accessible even when access to the setting menu is blocked by the code.

4.3 Control

The D1C can operate as a proportional controller or as a PID controller - dependent on the device version (see identity code) and the setting.

The controlled variable is recalculated once a second. Control procedures which require rapid correction of setpoint deviations (less than approx. 30 seconds) cannot be processed with this controller. The cycle times must be taken into consideration when activating solenoid valves (pulse length) in the same way as their running times when activating servomotors (3-point).

Via the control input pause, the control function (selection of controlled variable) can be switched off. The calculation of the controlled variable starts again after cessation of "pause".

Feed Forward Control 4.4

The D1C controller can process a signal of a feed forward control. Depending on the device version (see identity code) and the setting, this signal can be obtained in any form of a 0-20 mA or 4-20 mA signal or as a digital contact signal with the maximum frequencies 10 Hz or 500 Hz.

This signal can be used, for example, for flow-proportional metering (multiplicative effect) or feed forwarddependent basic load metering (additive effect). The result of control variable calculation from the proportional or PID control is multiplied by or added to the feed forward signal. A multiplicative feed forward variable at the level of the set rated value carries over the calculated control variable unchanged into the controlled variable:

Control variable = Feed forward variable/rated value x calculated control variable

During start-up, the zero point has to be checked. The multiplicative feed forward control is not designed for switching off permanently the actuating variable (signal \approx 0).

An additive feed forward variable at the level of the rated value results in maximum control variable:

Control variable (max, 100 %) = Feed forward variable/rated value x max, control variable + calculated control variable

4.5 Error Messages

Error messages and information are indicated on the bottom line in the permanent display 1. Errors to be

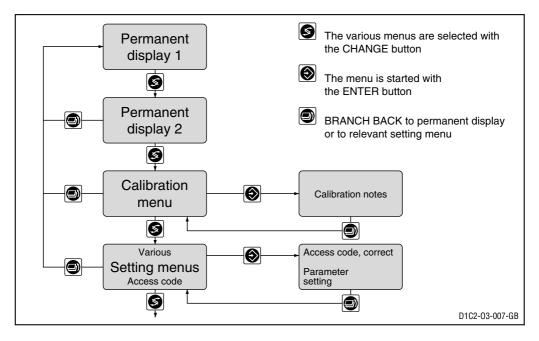
acknowledged (acknowledgement switches off the alarm relay) are indicated by the " \mathcal{E} ". Errors/notes which still apply after acknowledgement are indicated alternately. During correction variable processing (temperature for correction of pH-value), the value is indicated in the same line as the error/note. Faults which are rectified of their own accord due to changed operating situations are removed from the permanent display without the need for acknowledgement.

5 Display Symbols

The display of the DULCOMETER® D1C controller uses the following symbols:

Description	Comment	Symbol	
Limit value transgression Relay 1, upper	Symbol left	1	
Relay 1, lower	Symbol left	ŀ	
Relay 2, upper	Symbol right	1	
Relay 2, lower	Symbol right	ŀ	
Metering pump 1 (ozone) Control off	Symbol left		
Control on	Symbol left		
Metering pump 2 (De-ozone) Control off	Symbol right		
Controll on	Symbol right		
Solenoid valve 1 (ozone) Controll off	Symbol left		
Controll on	Symbol left	Δ	
Solenoid valve 2 (De-ozone) Controll off	Symbol right		
Control on	Symbol right		
Servomotor Control, open relay			
Control, close relay			
Without control			
Position feedback	Thickness of bar increases from left to right during opening		
Stop button pressed		0	
Manual metering		M	
Fault		5	

6 Operation



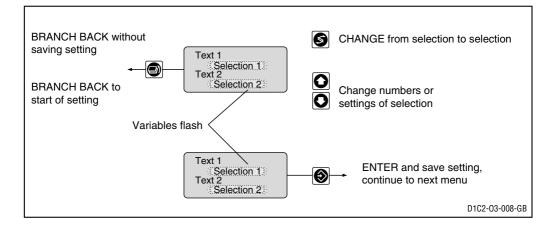
NOTE

Access to the setting menus can be barred with the access code!

The number and scope of setting menus is dependent on the device version!

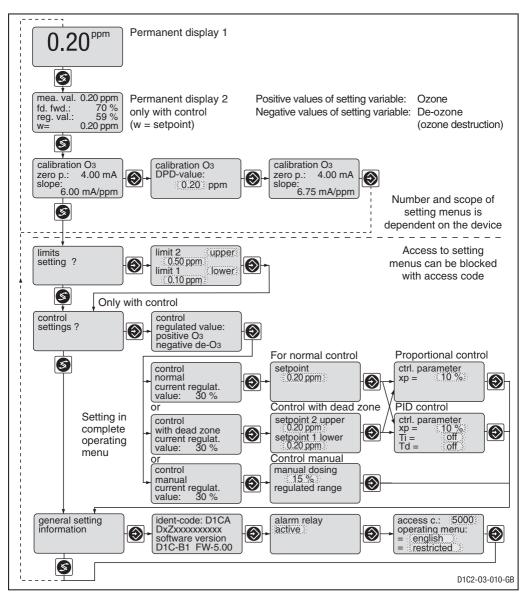
If the access code is selected correctly in a setting menu, then the following setting menus are also accessible!

If within a period of 10 minutes no button is pushed, the unit automatically branches back from the calibrating menu or a setting menu to the permanent display 1!

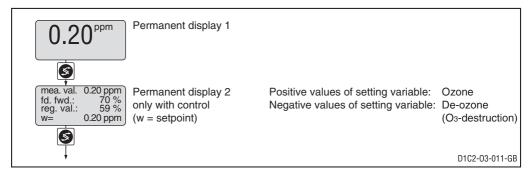


7 Restricted Operating Menu / Layout

The restricted operating menu permits simple operation of the most important parameters. The following overview shows the settings which can be selected.



Restricted Operating Menu / Description



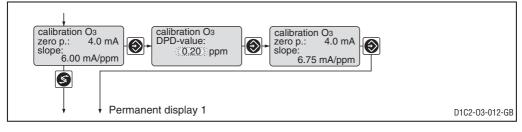
Calibration the Ozone Probe

During the calibration, the D1C sets the control variable to "0". Exception: If a base load or manual control variable was set, these are maintained during the calibration. The standard signal outputs mA (measured value or correction value) are frozen. The measured value registered during the start of the calibration is proposed as the DPD value; this value is adjustable (arrow keys). Calibration is only possible if the DPD value is ≥ 2 % of the measuring range. On successful completion of calibration, all error checks which refer to the measured value are restarted.



IMPORTANT

The measuring range of the probe must agree with the set measuring range (factory setting: 0-2 ppm). The measuring range must be reset prior to calibration (refer to page 14 "Measured value setting").

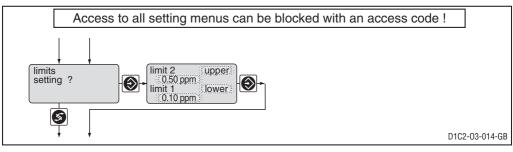


		Possible values	S		
	Initial value	Increment	Lower value	Upper value	Remark
	Measured value	0.01 ppm	0 ppm	20 ppm	

Error message	Condition	Remarks
Calibration O_3 not possible! Probe slope too low	0_3 slope too low (<25% of norm slope)	Calibrate again
Calibration O_3 not possible! Probe slope too high	0_3 slope too high (>300% of norm slope)	Calibrate again
DPD value too low DPD > x.xx ppm	DPD <2 % of the measuring range	Calibrate again after adding ozone

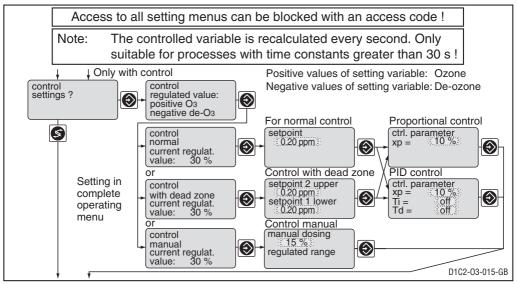
Restricted Operating Menu / Description

Limits



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remark
5	ns- nit 1: lower nit 2: upper	upper lower off*			Limit transgression when exceeding or dropping below value *only with limit relays
	nit 1: 0.1 ppm nit 2: 0.5 ppm	0.01 ppm 0.01 ppm	0.00 ppm 0.00 ppm	20.00 ppm 20.00 ppm	

Control



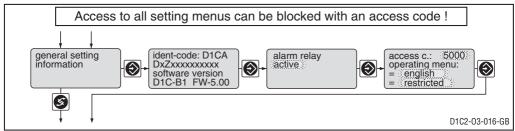
Restricted Operating Menu / Description

		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Setpoint	0.20 ppm	0.01 ppm	lower limit measuring range	upper limit measuring range	2 setpoints necessary for control with dead zone. Setpoint 2 < Setpoint 1
Control parameter xp	10 %	1 %	1 %	500 %	xp referred to measuring range
Control parameter Ti	off	1 s	1 s	9999 s	Function off $= 0$ s
Control parameter Td	off	1 s	1 s	2500 s	Function off = 0 s
Manual metering	15 %	1 %	-100 %	+100 %	

Abbreviation for control variables:

- $\begin{array}{l} x_{p}=100 \ \%/Kp \ (inverse \ proportional \ co-efficient) \\ T_{i}^{}=I \ controller \ integration \ time \ [s] \\ T_{d}^{}=D \ controller \ differential \ time \ [s] \end{array}$

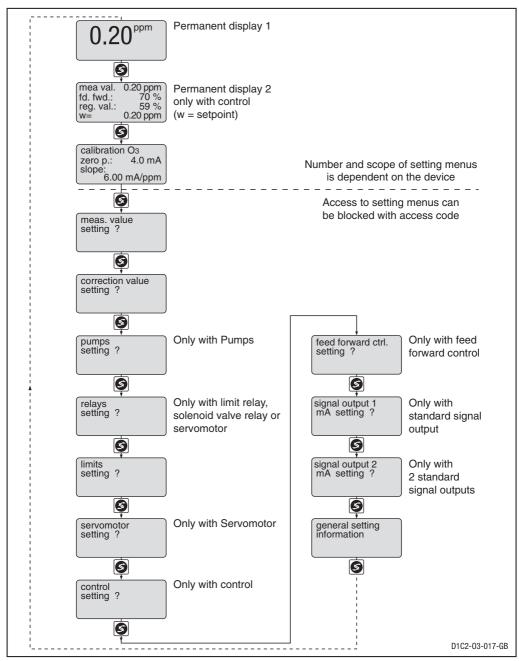
General Settings

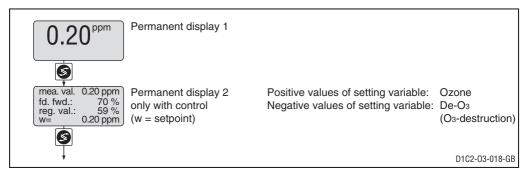


	Initial value	Possible values Increment	Lower value	Upper value	Remarks
Alarm relay	active	active not active			
Access code	5000	1	1	9999	
Language	as per identity code	as per identity code			
Operating menu	restricted	restricted complete			

Access Code

Access to the setting menu can be prevented by setting up an access code. The DULCOMETER® D1C controller is supplied with the access code 5000 which permits free access to the setting menu. The calibration menu remains freely accessible even when access to the setting menu is blocked by the code. All parameters of the controller can be set in the complete operating menu (Access, see previous page). The following overview shows the settings which can be selected:





Calibration the Ozone Probe

During the calibration, the D1C sets the control variable to "0". Exception: If a base load or manual control variable was set, these are maintained during the calibration. The standard signal outputs mA (measured value or correction value) are frozen. The measured value registered during the start of the calibration is proposed as the DPD value; this value is adjustable (arrow keys). Calibration is only possible if the DPD value is ≥ 2 % of the measuring range. On successful completion of calibration, all error checks which refer to the measured value are restarted.



IMPORTANT

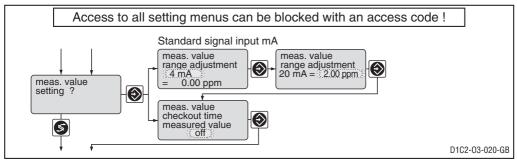
The measuring range of the probe must agree with the set measuring range (factory setting: 0-2 ppm). The measuring range must be reset prior to calibration (refer to page 14 "Measured value setting").

calibration O3 zero p.: 4.00 mA slope: 6.00 mA/ppm		
	rmanent display 1	D1C2-03-019-GB

		Possible values			
	Initial value	Increment	Lower value	Upper value	Remark
	Measured value	0.01 ppm	0 ppm	20 ppm	

Error message	Condition	Remark
Calibration O_3 not possible! Probe slope too low	0_3 slope too low (<25% of norm slope)	Calibrate again
Calibration O_3 not possible! Probe slope too high	0 ₃ slope too high (>300% of norm slope)	Calibrate again
DPD value too low DPD > x.xx ppm	DPD <2 % of the measuring range	Calibrate again after adding ozone

Measured Value





IMPORTANT

When changing the range adjustment, the ozone probe must be new calibrated and the adjustments in all menus have to be checked!

Measured value control period



IMPORTANT

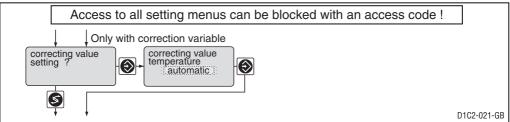
This function may not be activated for applications in which it can be assumed that the measured value will not change.

This function tests whether the measured value changes from that of the probe (at the measured value input) within the "Measured value control period". It is assumed that it will do so for an intact probe.

If the measuring value does not change during this control time, the DULCOMETER[®] D1C sets the control variable to "0" and the alarm relay drops out. The LCD display shows e.g. the message "Check O_3 probe".

		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Standard signal input lower signal limit	4 mA	0 mA 4 mA			
Allocated measured value lower upper	0 ppm 2 ppm	0.01 ppm	0.00 ppm	20.00 ppm	
Checkout time	off	1 s	1 s	9999 s	Constant measurement signal results in message and alarm. Function off = 0 s

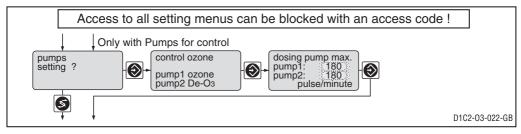
Correction Variable*



*The setting menu "Correction variable" enables this device to display the temperature or to receive a temperature-proportional mA signal. There will be no temperature correction of the measured value!

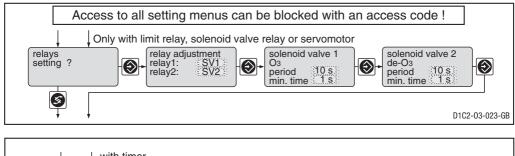
		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Type of temperature compensation	as per identity code	Manual Automatic off			Changeover only if specified in identity code = automatic
Manual temperature compensation	25 °C	0.1 °C	0 °C	100 °C	

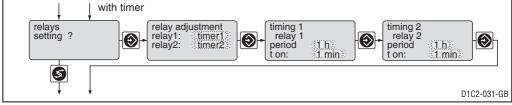
Pumps



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Max. stroke/minute of pumps 1 and 2	180	1	1	500	off = 0 strokes/min

Relay for power control

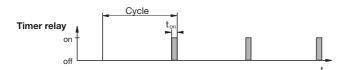




		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Relay adjustment	as per identity code				
Relay 1		Solenoid valve 1 Limit value 1* Actuator 1 Timer 1 Servomotor off			*At "limit value" the relays remain active also in the case of fault. Only with servomotor
Relay 2		Solenoid valve 2 Limit value 2* Actuator 2 Timer 2 off			
Cycle min. time	10 s 1 s	1 s 1 s	10 s 1 s	9999 s Cycle/2	for solenoid valve for solenoid valve
					Set here the smallest permitted operating factor of the connnected device.
Cycle	off	1 h	1 h/off	240 h	for timer
t on	1 min	1 min	1 min	60 min	for timer

NOTE

The limit value relay can be defined in such a way as to respond as a control element, i.e. if a limit value relay closes a circuit, it opens when a pause contact is activated and/or for a subsequent delay period t_a (if t_a is set to > 0 min in "General settings").





IMPORTANT

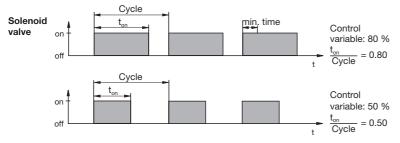
The timer will be reset if there is a drop in the power supply.

At the end of the (timer) cycle time, the DULCOMETER[®] D1C closes the assigned relay for the duration of "t on" (timer). "Pause" interrupts the timer.

When the clock is shown in the LC display, the timer can be reset to the start of the cycle at precisely this point using the enter button.

The % figure in the LC display indicates the progress of the current cycle.

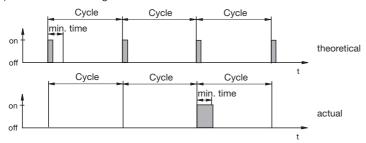
Timer relays may be used, e.g. for shock metering or sensor cleaning.



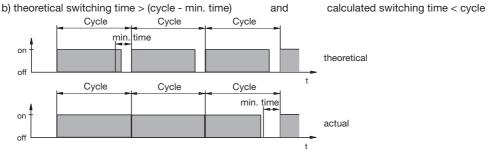
The switching time of the DULCOMETER® D1C (solenoid valve) depends on the actuating variable and the "min. time" (smallest permitted operating factor of the connected device).

The actuating variable determines the ratio t_{or}/cycle and thus the switching times (see fig. above). The "min. time" influences the switching times in two situations:

a) theoretical switching time < min. time:

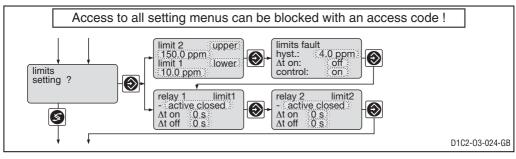


The DULCOMETER® D1C does not switch for a certain number of cycles until the sum of the theoretical switching times exceeds the "min. time". Then the DULCOMETER® D1C switches for the duration of this total time.



The DULCOMETER® D1C does not deactivate for a certain number of cycles until the differences between cycle and theoretical switching time exceed the "min. time".

Limits



		Initial value	Possible values Increment	Lower value	Upper value	Remarks
Type of limit gression	trans- Limit 1: Limit 2:	lower upper	upper lower off*			Limit transgression when exceeding or dropping below value *only with limit relays
Limit value	Limit 1: Limit 2:	0.10 ppm 0.50 ppm	0.01 ppm 0.01 ppm	0.00 ppm 0.00 ppm	20.00 ppm 20.00 ppm	
Hysteresis lin	nits	0.04 ppm	0.01 ppm	0.02 ppm	20.00 ppm	Effective in direction of "cancelling limit transgression"
Checkout tim	e limits t on	off	1 s	off	9999 s	Results in message and alarm. off = 0 s:
						Function switched off, no message, no alarm.
Control		on	on off			
Switching dir Limit value 1	ection , Limit value 2	active closed	active closed active open			Acts as N/O Acts as N/C
Switch-on de	lay ∆t_on	0 s	1 s	0 s	9999 s	
Switch-off de	elay ∆t_off	0 s	1 s	0 s	9999 s	

If the limit is exceeded for longer than the "delay time - limit values" an error message is given, which must be acknowledged, and the alarm relay circuit is broken. If "control" is also set to "off" the control process stops.

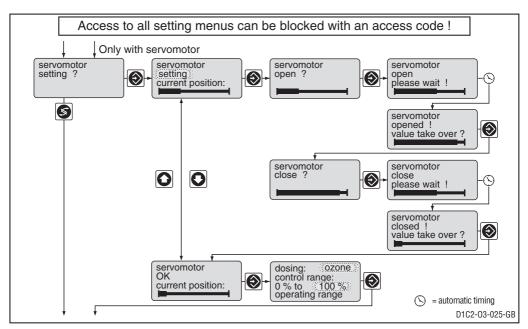
Servomotor

The **operating range** is defined by the total resistance range of the feedback potentiometer. The maximum limit of the range actually used is set by defining the **control range**.



IMPORTANT

- To ensure correct operation, the activation time of the actuator used should not be less than 25 seconds for the control range from 0...100 %!
- Activation of the servomotor must be carried out with the same meticulous care as taken when calibrating a measuring probe.

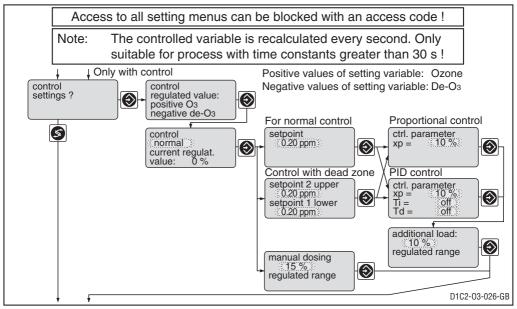


		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Servomotor	setting	setting OK off			
Control direction	Ozone	Ozone de-ozone			
Control range	100 %	1 %	10 %	100 %	in % of operating range

NOTE

- When the wide bar is as right as it will go the stroke adjustment motor is fully open.
- The permanent display shows to what degree the motor has opened in % (the greater the percentage, the farther open the stroke adjustment motor.)

Control



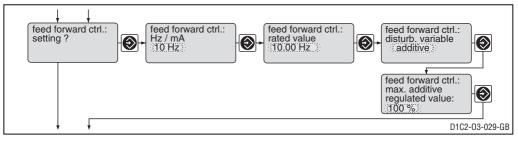
		Possible value	es		
	Initial value	Increment	Lower value	Upper value	Remarks
Control	normal	normal with dead zone manual			When controlling with dead zone, the feed forward control is not used for measured values within the dead zone.
Setpoint	0.20 ppm	0.01 ppm	Lower measure- ment range limit	Lower measure- ment range limit	2 setpoints necessary for control with dead zone. Setpoint 1 < setpoint 2
Control parameter xp	10 %	1 %	1 %	500 %	xp referred to measuring range
Control parameter Ti	off	1 s	1 s	9999 s	Function off= 0 s
Control parameter Td	off	1 s	1 s	2500 s	Function of $f = 0$ s
Additional load	0 %	1 %	-100 %	+100 %	
Manual metering	15 %	1 %	-100 %	+100 %	

Abbreviation for control variables:

 $x_p = 100$ %/Kp (inverse proportional co-efficient)

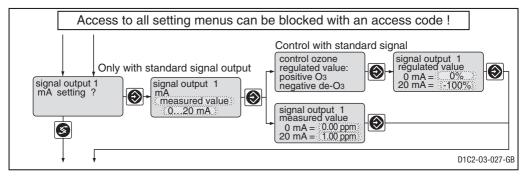
- $T_{i}^{p} = I$ controller integration time [s]
- $T_{d} = D$ controller differential time [s]

Feed forward control

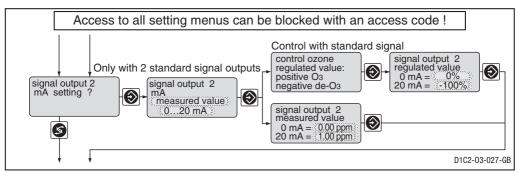


		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Feed forward control (Flow)	as per identity code Standard signal 4-20 mA	None 10 Hz 500 Hz 020 mA 420 mA			Signal processing: Signal <0,02 Hz = No flow Signal <0,2 Hz = No flow Signal <0,2 mA = No flow Signal <4,2 mA = No flow
Feed forward control rated value	10 Hz 500 Hz 20 mA	0.01 Hz 1 Hz 0.1 mA	0.1 Hz 5 Hz 0/4 mA	10 Hz 500 Hz 20 mA	Depended on signal type. Maximum limitation of range used.
Feed forward control effect	multiplicative	multiplicative additive			
Max. additive regulated value	100 %	1 %	-500 %	+500 %	only with additive feed forward control

Standard Signal Output 1

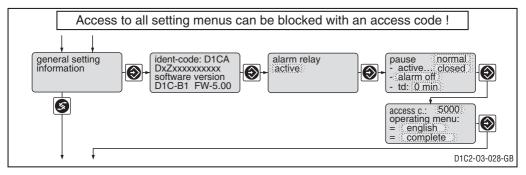


Standard Signal Output 2



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Variable allocation	as per identity code	Measured value Controlled variable Correction value			If control applicable only with correction variable
Output range	020 mA	020 mA 420 mA 3.6/4-20 mA			Reduction to 3.6 mA when alarm relay switches (not limit value violation)
Range measured value	05 ppm	0.01 ppm	0 ppm	11.00 ppm	Minimum range 0.1 ppm
Range controlled variable	0 %100 %	1 %	-100 %	+100 %	Minimum range 1 %

General setting



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Alarm relay	active	active not active			
Pause	Normal	Normal Hold			
Control input pause	active closed	active closed active open			
Alarm Pause	Alarm off	Alarm off Alarm on			Alarm relay can be triggered by pause contact
td	0 min	1 min	0 min	60 min	
Access code	5000	1	1	9999	
Language	as per identity code	as per identity code			
Operating menu	complete	restricted complete			

Pause Normal

If the pause-switch is off, the DULCOMETER[®] D1C sets the operating outputs to "0" for as long as the pause-switch is off or for a set time-delay t_d (if t_d is set to > 0 min). Whilst the pause-switch is off, the D1C establishes the P-proportion in the background.

With PID-control (Identity code characteristics "control characteristic" = 2): the I-proportion is stored when the pause is switched off (I-proportion then usually only present if Ti > 0 has been selected in the "Control setting?" setting menu).

Exception: the standard signal outputs mA for the measured value or correction value are not affected by the pause.

After pause is activated the operating outputs remain at "0" for the length of the time-delay t_d . The time-delay t_d must be set up in such a way that, in this time e.g. sample water (process-specific current concentration) flows to the sensor.

With PID-control (Identity code characteristics "control characteristic" = 2): The control variable output resulting from the pause and the expiry of the time-delay t_d is reconciled jointly with the current P-component and (if Ti is set > 0) with the stored I-component.

Pause Hold

If the pause-switch is off, the DULCOMETER[®] D1C freezes the operating output at the most recent value for as long as the pause-switch is off or for a set time-delay t_d (if t_d is set to > 0 min). Whilst the pause-switch is off, the D1C establishes the P-proportion in the background.

With PID-control (Identity code characteristics "control characteristic" = 2):

Even the mA standard signal outputs for measured value or correction value are frozen.

After pause is activated the operating outputs remain frozen for the length of the time delay t_{d} . The time delay t_{d} must be set up in such a way that, in this time e.g. sample water (process-specific current concentration) flows to the sensor.

With PID-control (Identity code characteristics "control characteristic" = 2): The control variable output resulting from the pause and the expiry of the time-delay t_d is reconciled jointly with the current P-proportionand (if Ti is set > 0) with the newly established I-proportion.

Access Code

Access to the setting menu can be prevented by setting up an access code. The DULCOMETER[®] D1C controller is supplied with the access code 5000 which permits free access to the setting menu. The calibration menu remains freely accessible even when access to the setting menu is blocked by the code.

:	1)			-	3	7
rault	רמטונ נפאנ	oyiiiuui	on metering or	on control	Alarni willi acknowledgement	neillarks	кылыму
Measured value Checkout time measured value exceeded	Check O_3 probe	Μ	Basic load	Stop	Yes	Function defeatable	Check function of probe, extend check time
Signal exceeded/drops below value	Check O_3 input $\uparrow \downarrow$	m	Basic load	Stop	Yes	Signal <3.0 ±0.2 mA or >23 ±0.2 mA	Check probe, transducer and cable connection
Calibration probe with error	Check O ₃ calibration	Μ	Basic load	Stop	No	Metering continues in case of error with unsteady measured values	Check probe, replace if necessary, recalibrate if necessary
Correction variable Signal exceeded/drops below value	Check te-input	m	Basic load	Stop	Yes	Pt100-signal >138.5 Ω Signal <3.0 \pm 0.2 mA or >23 \pm 0.2 mA Value last valid is used	Check probe, transducer and cable connection
Feed forward control Signal exceeded/drops below value	Check feed forward input	Μ			Yes	Signal <4.0 \pm 0.2 mA or >23 \pm 0.2 mA Value last valid is used	Check probe, transducer and cable connection
Limit transgression after checkout time limits Control "on" Control "off"	O_3 limit 1 + O_3 limit 2 +	ΜM	Stop or Basic load	Stop	Yes Yes	Function defeatable	Define cause, reset values if necessary
Servomotor Position not reached	Servomotor defective	m			Yes	Servomotor closes	Check servomotor
Electronics error	System error	т О	Stop	Stop	Yes	Elektronic data defective	Call in service
Operation	Note text	Symbol	Effect on metering on control	ect on control	Alarm with acknowledgement	Remarks	Remedy
Pause contact	Pause	m O	Stop	Stop	No/Yes*	No further fault check	I
	Pause/Hold	m		PI-component frozen			
Stop button	Stop	m O	Stop	Stop	No	Relay drops out	I
During calibration Probe			Basic load	Stop	No	No error processing of measured variable	I
Probe slope too low Probe slope too high	Slope O_3 low Slope O_3 high	Μ	Basic load	Stop	No	25% > probe slope > 300% of norm slope	Check probe, replace if necessary
DPD value <2 % measuring range	DPD value too low				No		Recalibrate after adding 0_3
During servomotor setting Position feed back wrong Upper position <40 % max. value Lower position >30 % range *depending on whether "Alarm on"	Direction check Final value small Final value big or "Alarm off" set in "	General se	sttiings"			Without correct adjustment the last valid values are still used	Check connection of relay, potentiometer. Adjust the operation region of the servomotor correctly
*depending on whether "Alarm on" or "Alarm off" set in "General settings"	or "Alarm off" set in "	General se	ottings"				

9 Faults / Remarks / Troubleshooting

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