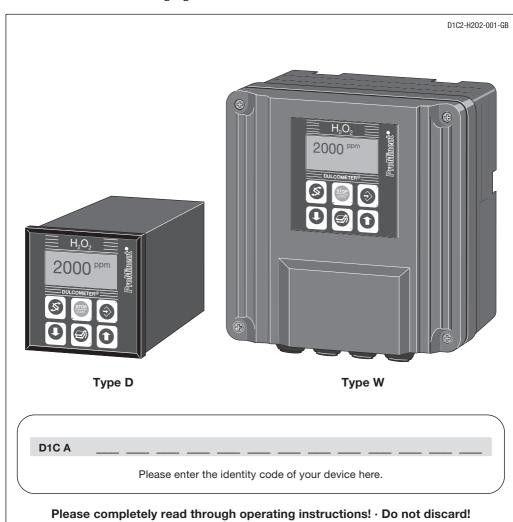
ProMinent®

Operating Instructions

DULCOMETER® D1C

Part 2: Adjustment and Operation, Measured variable H₂O₂ for sensor PER 1





The warranty shall be invalidated by damage caused by operating errors!

1 Device Identification / Identity Code

D1CA DUI	LCOMET	TER® Co	ntroll	er Seri	ies D	1C /	Versi	on A					
	Туре	of mou	ınting										
D		rol pane			96 x 9	96 m	m						
W	Wall	mountin	ıg										
		Opera	ating	voltage	Э								
	0	230 V	50/60	Hz									
	1	115 V	50/60	Hz									
	2	200 V	50/60	Hz (or	nly wi	th co	ntrol	panel i	nstallati	on)			
	3								nstallati				
	4		AC/DC							,			
			Mea	sured	varia	ble							
		Н	Hyd	rogen p	oeroxi	de F	I ₂ O ₂						
								asured	variabl	е			
			7	Terr	ninal,	stan	dard	signal	0/4-20 r	nA for	sensor	PER 1	
					Co	orre	ction	variab	е				
				0	No	ne							
				2	Te	mpe	rature	via te	rminal				
				3	Te	mpe	ratura	via st	andard :	signal			
				4	ma	anua	l tem	oeratur	e input				
				\neg			Feed	forwa	rd cont	rol			
					C)	None						
					1		via st	andard	signal	0/4-20	mΑ		
					2				y 0-500				
					3	3	via fr	equend	y 0-10	Hz			
								Con	trol inpu	ıt			
							0	None	9				
							1	Paus	e				
									Signa	al outp	ut		
								0	None				
								1					A measured value
								2					A control variable
1 1								3					A correction variable
								4	2 sta				nA outputs, free programmable
											er con		
									G				alue/timer relays
									M				oid valve relays
									R	Alarn			rvomotor with feedback
1 1												p cont	rol
1 1										0	Non		
										2	TWO	pumps	
													trol characteristic
											0	None	
											1		portional control
											2	I PID	control Log output
												0	None
												<u> </u>	Language
													D German
													E English
													F French
													I Italian
													N Dutch
													S Spanish
													B Portuguese
													G Czech
													J Japanese
⊥	\perp	\perp		1	J		Τ	\perp	\perp	\perp	\perp	Τ.	<u> </u>
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2 Contents / General User Information

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General User Information

These operating instructions describe the technical data and function of the series DULCOMETER® D1C controller, provide detailed safety information and are divided into clear steps.



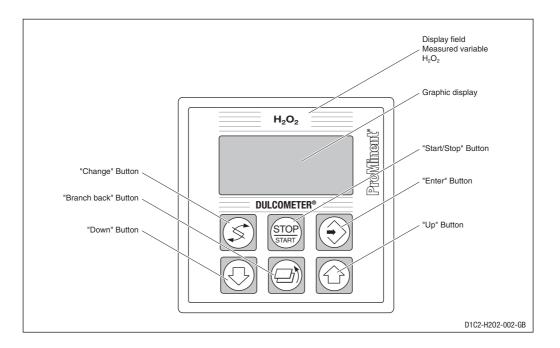
IMPORTANT

- Please observe the parts of these operating instructions applicable to your particular version! This is indicated in the Section "Device Identification / Identity Code"!
- Correct measuring and dosing is only possible in the case of impeccable operation of the probe. The probe has to be calibrated / checked regularly!

NOTE

A form "Documentation of controller settings Type D1C" is available under www.prominent.com/documentation_D1C for the purpose of documenting the controller settings.

3 Device Overview / Controls





CHANGE Button

To change over within a menu level and to change from one variable to another within a menu point.



START/STOP Button

Start/stop of control and metering function.



ENTER Button

To accept, confirm or save a displayed value or status. For alarm acknowledgement.



UP Button

To increase a displayed numerical value and to change variables (flashing display).



BRANCH BACK Button

Back to permanent display or to start of relevant setting menu.



DOWN Button

To decrease a displayed numerical value and to change variables (flashing display).

4 Functional Description

NOTE

Please refer to the description of the complete operating menu in Section 8 for a detailed description of the individual characteristics of the DULCOMETER® D1C controller!

4.1 Operating Menu

The D1C controller permits settings to be made in two different menus. All values are preset and can be changed in the **complete operating menu**.

The controller is delivered with a **restricted operating menu** so that the D1C controller can be used effectively in many applications from the very onset. If adaptations prove to be necessary, all relevant parameters can then be accessed by switching over to the complete operating menu (see "General settings").

4.2 Access Code

Access to the setting menu can be prevented by setting up an access code. The D1C controller is supplied with the access code 5000 which permits free access to the setting menu. The calibration menu remains freely accessible even when access to the setting menu is blocked by the code.

4.3 Control

The D1C can operate as a proportional controller or as a PID controller - dependent on the device version (see identity code) and the setting.

The controlled variable is recalculated once a second. Control procedures which require rapid correction of setpoint deviations (less than approx. 30 seconds) cannot be processed with this controller. The cycle times must be taken into consideration when activating solenoid valves (pulse length) in the same way as their running times when activating servomotors (3-point).

Via the control input pause, the control function (selection of controlled variable) can be switched off. The calculation of the controlled variable starts again after cessation of "pause".

4.4 Feed Forward Control

The D1C controller can process a signal of a feed forward control. Depending on the device version (see identity code) and the setting, this signal can be obtained in any form of a 0–20 mA or 4–20 mA signal or as a digital contact signal with the maximum frequencies 10 Hz or 500 Hz.

During start-up, the zero point has to be checked. The multiplicative feed forward control is not designed for switching off permanently the actuating variable (signal \approx 0).

This signal can be used, for example, for flow-proportional metering (multiplicative effect) or feed forward-dependent basic load metering (additive effect). The result of control variable calculation from the proportional or PID control is multiplied by or added to the feed forward signal. A multiplicative feed forward variable at the level of the set rated value carries over the calculated control variable unchanged into the controlled variable:

Controlled variable = Feed forward variable/rated value x calculated control variable

An additive feed forward variable at the level of the rated value results in maximum controlled variable:

Controlled variable (max. 100 %) = Feed forward variable/rated value x max. controlled variable

+ calculated control variable

4.5 Error Messages

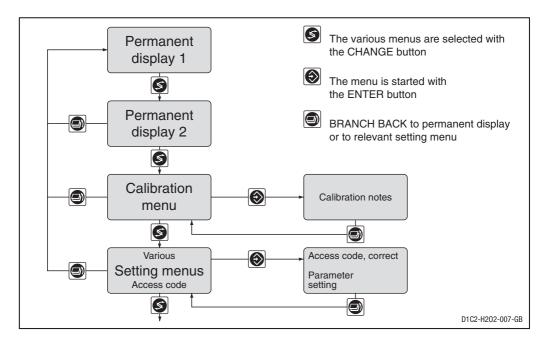
Error messages and information are indicated on the bottom line in the permanent display 1. Errors to be acknowledged (acknowledgement switches off the alarm relay) are indicated by the " ξ ". Errors/notes which still apply after acknowledgement are indicated alternately. During correction variable processing (temperature for correction of pH-value), the value is indicated in the same line as the error/note. Faults which are rectified of their own accord due to changed operating situations are removed from the permanent display without the need for acknowledgement.

5 Display Symbols

The display of the DULCOMETER $\hskip-3pt^{\! \circ}$ D1C controller uses the following symbols:

Description	Comment	Symbol		
Limit value transgression Relay 1, upper	Symbol left	1		
Relay 1, lower	Symbol left	ļ		
Relay 2, upper	Symbol right	1		
Relay 2, lower	Symbol right	l l		
Metering pump 1 (H ₂ O ₂) Control off	Symbol left			
Control on	Symbol left			
Metering pump 2 (De-H ₂ O ₂) Control off	Symbol right			
Control on	Symbol right			
Solenoid valve 1 (H ₂ O ₂) Control off	Symbol left	4		
Control on	Symbol left	Δ		
Solenoid valve 2 (De-H ₂ O ₂) Control off	Symbol right	L		
Control on	Symbol right	<u> </u>		
Servomotor Control, open relay		⊿		
Control, close relay		△ ►		
Without control		4		
Position feedback	Thickness of bar increases from left to right during opening.			
Stop button pressed		0		
Manual metering		M		
Fault		3		

6 Operation



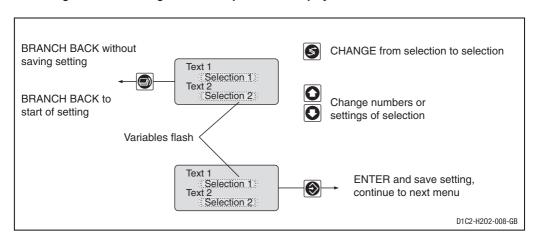
NOTE

Access to the setting menus can be barred with the access code!

The number and scope of setting menus is dependent on the device version!

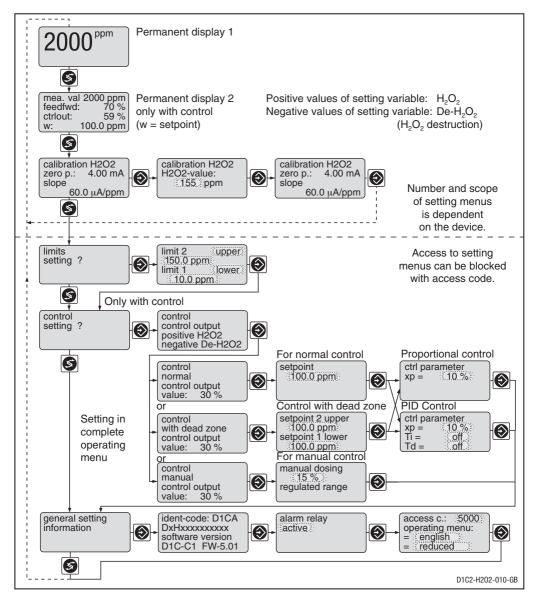
If the access code is selected correctly in a setting menu, then the following setting menus are also accessible!

If within a period of 10 minutes no button is pushed, the unit automatically branches back from the calibrating menu or a setting menu to the permanent display 1.

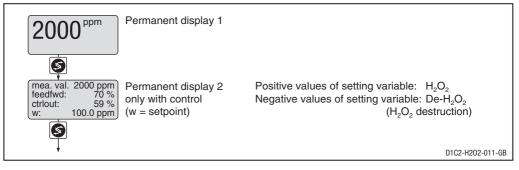


7 Restricted Operating Menu / Overview

The restricted operating menu permits simple operation of the most important parameters. The following overview shows the settings which can be selected:



Restricted Operating Menu / Description



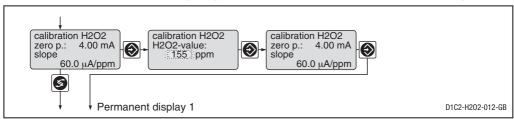
Calibration of the H₂O₂ probe

During calibration, the D1C sets the positioning outputs to "0". The exception to this is that when a base load or a manual controller output has been set, these are retained during the calibration. The mA standard output signals (measured value or correcting value) are frozen. The measured value frozen at the start of the calibration is suggested as the H_2O_2 value; this value is adjustable (arrow keys!). Calibration is only possible when the H_2O_2 value ≥ 2 % of the range. When the calibration is successfully completed, all fault diagnoses that relate to the measured value are started afresh.



IMPORTANT

The measuring range of the probe must agree with the set measuring range (factory setting: 0–200.0 ppm). The measuring range must be reset prior to calibration (refer to page 15).

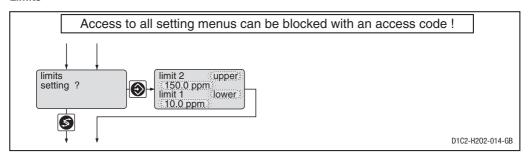


	Possible values			
Initial value	Increment	Lower value	Upper value	Remarks
Measured value	1 ppm	-2000 ppm	22000 ppm	for measurement range up to 20000 ppm
	1 ppm	-200 ppm	2200 ppm	for measurement range up to 2000 ppm
	0.1 ppm	-20 ppm	220 ppm	for measurement range up to 200 ppm

Error message	Condition	Effect
Calibration H ₂ O ₂ not possible! Probe slope too low	H ₂ O ₂ slope too low (<25 % of norm slope)	Calibrate again
Calibration H ₂ O ₂ not possible! Probe slope too high	H ₂ O ₂ slope too high (>300 % of norm slope)	Calibrate again
H_2O_2 value too low $H_2O_2 > x.xx$ ppm	H ₂ O ₂ <2 % measuring range	

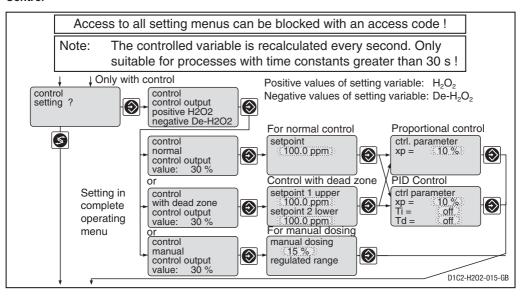
Restricted Operating Menu / Description

Limits



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Type of limit trans- gression Limit 1: Limit 2:	lower upper	upper lower off *)			Limit transgression when exceeding or dropping below value *) only with limit relays
Limit value Limit 1: Limit 2:	100 ppm 1500 ppm	1 ppm	-200 ppm	2200 ppm	
Limit 1: Limit 2:	10.0 ppm 150.0 ppm	0.1 ppm	-20.0 ppm	220.0 ppm	

Control



Restricted Operating Menu / Description

		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Setpoint	10000 ppm 1000 ppm 100.0 ppm	1 ppm 1 ppm 0.1 ppm	-1000 ppm -100 ppm -10.0 ppm	21000 ppm 2100 ppm 210.0 ppm	2 setpoints necessary for control with dead zone. Setpoint 1 > setpoint 2
Control parameter xp	10 %	1 %	1 %	500 %	xp referred to measuring range
Control parameter Ti	off	1 s	1 s	9999 s	Function off = 0 s
Control parameter Td	off	1 s	1 s	2500 s	Function off = 0 s
Manual metering	0 %	1 %	-100 %	+100 %	

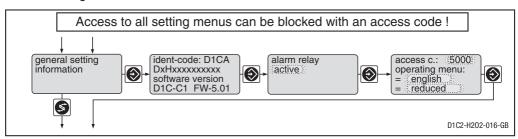
Abbreviations for control variables:

x_o: 100 %/Kp (inverse proportional coefficient)

T_i: Integration time of I-controller [s]

T_d: Differential time of D-controller [s]

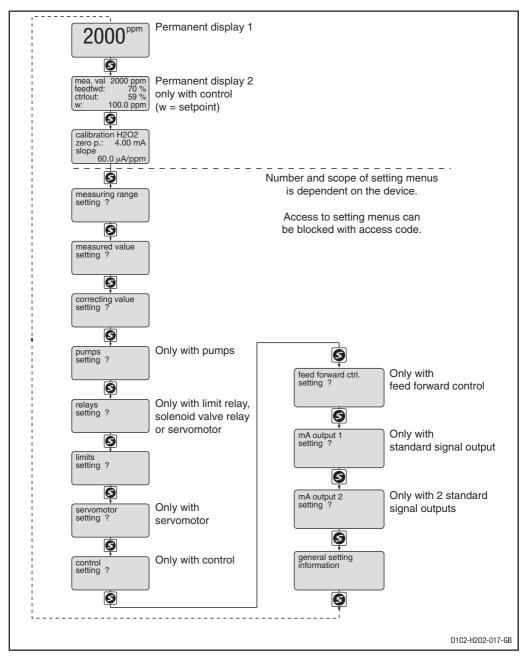
General Settings

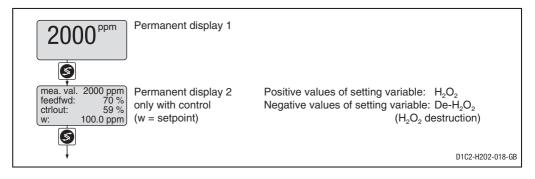


		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Alarm relay	active	active not active			
Access code	5000	1	1	9999	
Language	as per identity code	German English French Italian Dutch Spanish Portuguese Czech Japanese (as per identity code)			
Operating menu	restricted	restricted complete			

8 Complete Operating Menu / Overview

All parameters of the controller can be set in the complete operating menu (access see previous page). The following overview shows the settings which can be selected:





Calibration of the H₂O₂ Probe (zero point and slope)

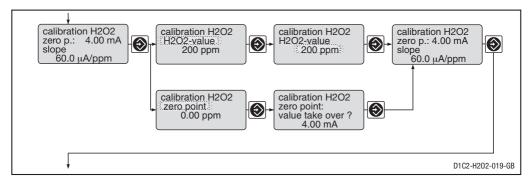
During calibration, the D1C sets the positioning outputs to "0". The exception to this is that when a base load or a manual controller output has been set, these are retained during the calibration. The mA standard output signals (measured value or correcting value) are frozen. The measured value frozen at the start of the calibration is suggested as the H_2O_2 value; this value is adjustable (arrow keys!). Calibration is only possible when the H_2O_2 value ≥ 2 % of the range. When the calibration is successfully completed, all fault diagnoses that relate to the measured value are started afresh.

The zero calibration must be made under realistic conditions in H_2O_2 -free water. This is normally only necessary when the measuring at the lower limit of the range.



IMPORTANT

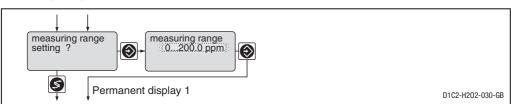
The measuring range of the probe must agree with the set measuring range (factory setting: 0–200.0 ppm). The measuring range must be reset prior to calibration (refer to page 14).



	Possible values			
Initial value	Increment	Lower value	Upper value	Remarks
Measured value	1 ppm	-2000 ppm	22000 ppm	for measurement range up to 20000 ppm
	1 ppm	-200 ppm	2200 ppm	for measurement range up to 2000 ppm
	0.1 ppm	-20 ppm	220 ppm	for measurement range up to 200 ppm

Error message	Condition	Effect	
Calibration H ₂ O ₂ not possible! Probe slope too low	H ₂ O ₂ slope too low (<25 % of norm slope)	Calibrate again	
Calibration H ₂ O ₂ not possible! Probe slope too high	H ₂ O ₂ slope too high (>300 % of norm slope)	Calibrate again	
H_2^0 02 value too low H_2^0 02 > x.xx ppm	H ₂ O ₂ <2 % of measuring range		
Zero point too low Zero point too high	< 3.7 mA > 5 mA	Check probe/cable Repeat calibration in H ₂ O ₂ -free water	

Measuring Range



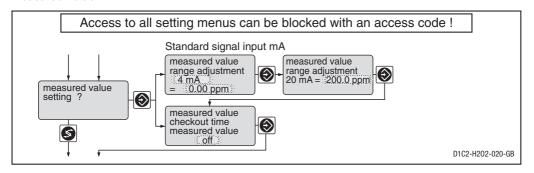
		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Measuring range	0200 ppm	0200 ppm 02000 ppm 020000 ppm			



IMPORTANT

If the area allocation is changed, the ${\rm H_2O_2}$ probe must be re-calibrated and all the menu settings must be checked!

Measured Value





IMPORTANT

If the area allocation is changed, the ${\rm H_2O_2}$ probe must be re-calibrated and all the menu settings must be checked!

Checkout time measured value



IMPORTANT

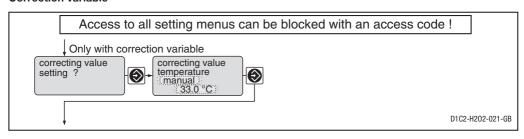
This function must not be enabled with applications where it can be assumed that the measured value does not change.

This function checks whether the measured value from the probe (at the measured value input) changes within the "measured value check time". It is assumed that it will change with an intact probe.

If the measured value does not change during this check time, the DULCOMETER® D1C sets the controller output to "0" and the alarm relay drops off. The "Check pH probe" message, for example, appears in the LCD display.

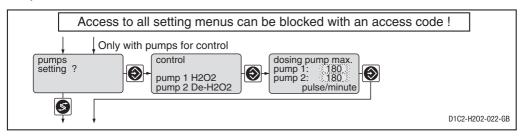
		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Standard signal input lower signal limit	4 mA	0 mA 4 mA			
Allocated measured value lower	0 0 0	1 ppm 1 ppm 0.1 ppm	-2000 ppm -200 ppm -20.0 ppm	22000 ppm 2200 ppm 220.0 ppm	
upper	2000 ppm 20000 ppm 200.0 ppm	1 ppm 1 ppm 0.1 ppm	-200 ppm -2000 ppm -20.0 ppm	2200 ppm 22000 ppm 220.0 ppm	
Checkout time	off	1 s	1 s	9999 s	Constant measurement signal results in message and alarm. Function off = 0 s

Correction variable



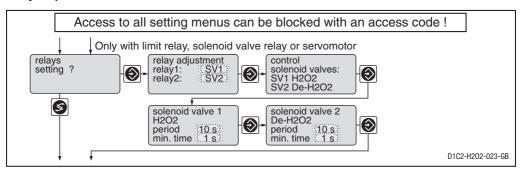
		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Type of temperature compensation	as per identity code	manual automatic off			Switching only when identity code shows = automatic
Manual temperature compensation	25 °C	0.1 °C	0 °C	100 °C	

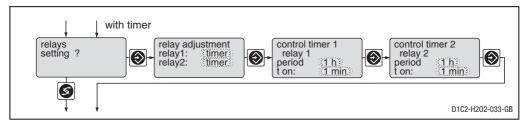
Pumps



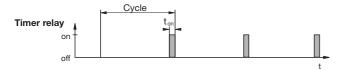
		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Max. stroke/minute of pumps 1 and 2	180	1	1	500	off = 0 strokes/min

Relay for power control





		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Relay adjustment	as per identity code				
Relay 1		Solenoid valve 1 Limit value 1* Actuator 1 Timer 1 Servomotor off			*For "limit value", the relays remain active, even in the event of a fault. only with servomotor
Relay 2		Solenoid valve 2 Limit value 2* Actuator 2 Timer 2 off			
Period (Cycle) min. time	10 s 1 s	1 s 1 s	10 s 1 s	9999 s Cycle/2	for solenoid valve for solenoid valve
Period (Cycle) t on	off 1 min	1 h 1 min	1 h / off 1 min	240 h 60 min	for timer for timer





IMPORTANT

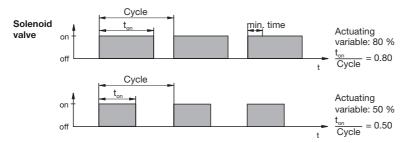
The timer will be reset if there is a drop in the power supply.

At the end of the (timer) cycle time the DULCOMETER® D1C closes the assigned relay for the duration of "t on" (timer). "Pause" interrupts the timer.

When the clock is shown in the LC display the timer can be reset to the start of the cycle at precisely this point using the enter button.

The % figure in the LC display indicates the progress of the current cycle.

Timer relays may be used, e.g. for shock metering or sensor cleaning.

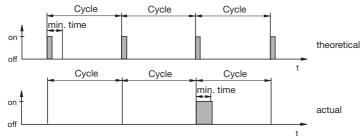


The switching time of the DULCOMETER® D1C (solenoid valve) depends on the actuating variable and the "min. time" (smallest permitted operating factor of the connected device).

The actuating variable determines the ratio t_{nn} /cycle and thus the switching times (see fig. above).

The "min. time" influences the switching times in two situations:

a) theoretical switching time < min. time:

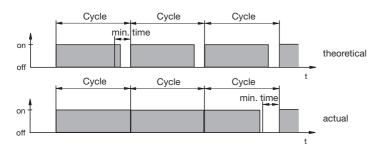


The DULCOMETER® D1C does not switch for a certain number of cycles until the sum of the theoretical switching times exceeds the "min. time". Then the DULCOMETER® D1C switches for the duration of this total time.

b) theoretical switching time > (cycle - min. time)

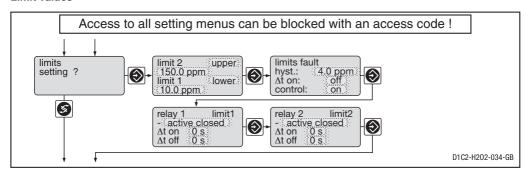
and

calculated switching time < cycle



The DULCOMETER® D1C does not deactivate for a certain number of cycles until the differences between cycle and theoretical switching time exceed the "min. time".

Limit values



			Possible values	S		
		Initial value	Increment	Lower value	Upper value	Remarks
Type of limit tra	unsgression Limit 1: Limit 2:	lower upper	upper lower off *)			Limit transgression when exceeding or dropping below value *) only with limit relay
Limit value	Limit 1: Limit 2:	150.0 ppm 10.0 ppm	0.1 ppm	-20.0 ppm	220.0 ppm	
	Limit 1: Limit 2:	1500 ppm 100 ppm	1 ppm	-200 ppm	2200 ppm	
Hysteresis limit	S	40 ppm 4.0 ppm	1 ppm 0.1 ppm	0 ppm 0 ppm	2200 ppm 220.0 ppm	Effective in direction of "Cancelling limit transgression"
Checkout time	limits ∆t on	off	1 s	1 s	9999 s	Results in message and alarm. off = 0 s: Function switched off, no message, no alarm
Control		on	on off			
Switching direct Limit value 1; L		active closed	active closed active open			Acts as N/O Acts as N/C
Switch-on delay Switch-off delay		0 s 0 s	1 s 1 s	0 s 0 s	9999 s 9999 s	

If the limit is exceeded for longer than the "Delay time - limit values" an error message is given, which must be acknowledged, and the alarm relay circuit is broken. If "Controller" is also set to "off" the control process stops.

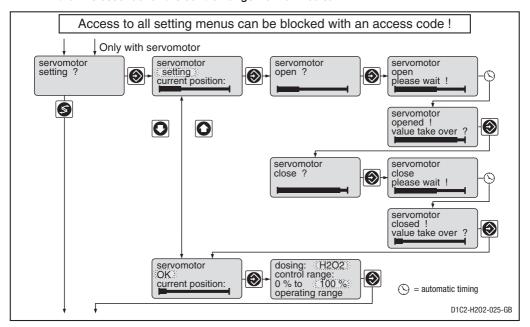
Servomotor

The **operating range** is defined by the total resistance range of the feedback potentiometer. The maximum limit of the range actually used is set by defining the **control range**.



IMPORTANT

- Activation of the servomotor must be carried out with the same meticulous care as taken when calibrating a measuring probe.
- To ensure correct operation, the activation time of the actuator used should not be less than 25 seconds for the control range from 0...100 %!

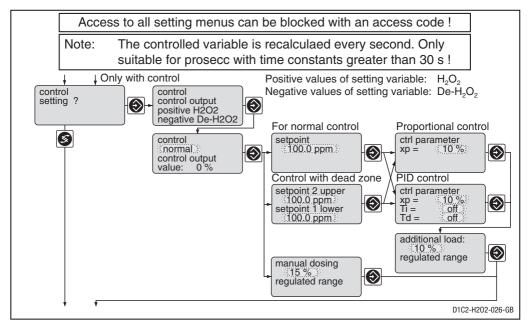


		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Servomotor	setting	setting ok off			
Control direction	H ₂ O ₂	H ₂ O ₂ De-H ₂ O ₂			
Control range	100 %	1 %	10 %	100 %	in % of operating range

NOTE

- When the wide bar is as far right as it will go the stroke adjustment motor is fully open.
- The permanent display shows to what degree the motor has opened in % (the greater the percentage, the farther open the stroke adjustment motor).

Control



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Control	normal	normal with dead zone manual			When controlling with dead zone, the regulated value is not used for measured values within the dead zone.
Setpoint setting	1000 ppm 100.0 ppm	1 ppm 0.1 ppm	-100 ppm -10.0 ppm	2100 ppm 210.0 ppm	2 setpoints necessary for control with dead zone.
					Setpoint 2 ≥ Setpoint 1
Control parameter xp	10 %	1 %	1 %	500 %	xp referred to measuring range
Control parameter Ti	off	1 s	1 s	9999 s	Function off = 0 s
Control parameter Td	off	1 s	1 s	2500 s	Function off = 0 s
Additional basic load	0 %	1 %	-100 %	+100 %	
Manual metering	0 %	1 %	-100 %	+100 %	

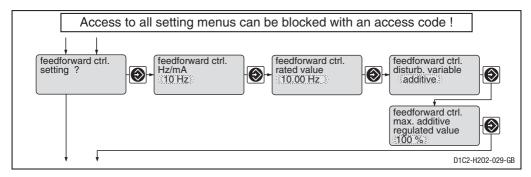
Abbreviations for control variables:

x_o: 100 %/Kp (inverse proportional coefficient)

T: Integration time of I-controller [s]

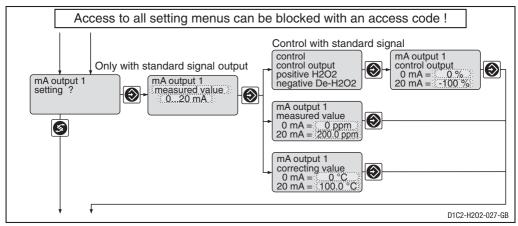
T_d: Differential time of D-controller [s]

Feed forward control

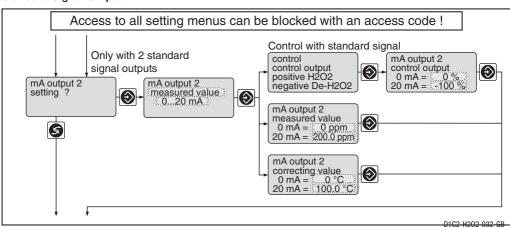


		Possible values		i	
	Initial value	Increment	Lower value	Upper value	Remarks
Feed forward control (Flow)	as per identity code at standard signal: 4–20 mA	None 10 Hz 500 Hz 020 mA 420 mA			Signal processing: Signal <0.02 Hz = No flow Signal <0.2 Hz = No flow Signal <0.2 mA = No flow Signal <4.2 mA = No flow
Feed forward control rated value	10 Hz 500 Hz 20 mA	0.01 Hz 1 Hz 0.1 mA	0.1 Hz 1 Hz 0/4 mA	10 Hz 500 Hz 20 mA	Depended on signal type. Maximum limitation of range used.
Feed forward control effect	multiplicative	multiplicative additive			
Max. add. regulated value	100 %	1 %	-500 %	+500 %	only with add. feed forward control

Standard Signal Output 1

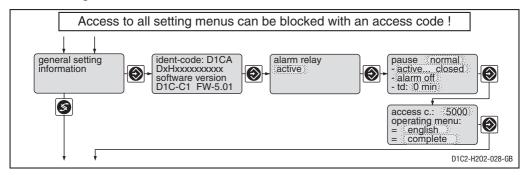


Standard Signal Output 2



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Variable allocation	as per identity code	Measured value Control output variable Correcting value			If control is present only with correcting variable
Output range	020 mA	020 mA 420 mA			
Range measured value	02000 ppm 0200.0 ppm	1 ppm 0.1 ppm	-200 ppm -20.0 ppm	2200 ppm 220.0 ppm	Minimum range 1 %
Range control output variable	-100 %0 %	1 %	-100 %	+100 %	Minimum range 1 %
Range correcting value	0100 °C	0.1 °C	0 °C	100 °C	Minimum range 1 °C

General setting



		Possible values	1		
	Initial value	Increment	Lower value	Upper value	Remarks
Alarm relay	active	active not active			
Pause	normal	normal hold			
Control input pause	active closed	active closed active open			acts as N/O acts as N/C
Pause alarm	alarm off	alarm off alarm on			Alarm relay can be activated by pause contact.
td	0 min	1 min	0 min	60 min	
Access code	5000	1	1	9999	
Language	as per identity code	German English French Italian Dutch Spanish Portuguese Czech Japanese (as per identity code)			
Operating menu	complete	restricted complete			

Standard Pause

If the pause-switch is off, the DULCOMETER® D1C sets the operating outputs to "0" for as long as the pause-switch is off or for a set time-delay t_d (if t_d is set to > 0 min). Whilst the pause-switch is off, the D1C establishes the P-proportion in the background.

With PID-control (Identity code characteristics "control characteristic" = 2): the I-proportion is stored when the pause is switched off (I-proportion then usually only present if Ti > 0 has been selected in the "Control setting?" setting menu).

Exception: the standard signal outputs mA for the measured value or correction value are not affected by the pause.

After pause is activated the operating outputs remain at "0" for the length of the time-delay t_d . The time-delay t_d must be set up in such a way that, in this time e.g. sample water (process-specific current concentration) flows to the sensor.

With PID-control (Identity code characteristics "control characteristic" = 2): The control variable output resulting from the pause and the expiry of the time-delay t_d is reconciled jointly with the current P-component and (if Ti is set > 0) with the stored I-component.

Pause Hold

If the pause-switch is off, the DULCOMETER® D1C freezes the operating output at the most recent value for as long as the pause-switch is off or for a set time-delay t_a (if t_a is set to > 0 min). Whilst the pause-switch is off, the D1C establishes the P-proportion in the background.

With PID-control (Identity code characteristics "control characteristic" = 2):

Even the mA standard signal outputs for measured value or correction value are frozen.

After pause is activated the operating outputs remain frozen for the length of the time delay t_a . The time delay t_a must be set up in such a way that, in this time e.g. sample water (process-specific current concentration) flows to the sensor.

With PID-control (Identity code characteristics "control characteristic" = 2): The control variable output resulting from the pause and the expiry of the time-delay t_d is reconciled jointly with the current P-proportion and (if Ti is set > 0) with the newly established I-proportion.

9 Fault / Remarks / Troubleshooting

Fault	Fault text	Symbol	Effect on metering on control	ect on control	Alarm with ack- nowledgement	Remarks	Remedy
Measured value Checkout time measured value exceeded	Check H ₂ O ₂ sensor	Μ	Basic load	Stop	Yes	Function defeatable	Check function of probe, extend check time
Signal exceeded/drops below value	H_2O_2 input < 3 mA H_2O_2 input > 23 mA	Э	Basic load	Stop	Yes	Signal $<3.0\pm0.2$ mA or $>23\pm0.2$ mA	Check probe, transducer and cable connection
Calibration probe with error	$H_2^{}O_2^{}$ calib. defective	3	Basic load	Stop	No	Metering continues in case of error with unsteady measured values	Check probe, replace if necessary, recalibrate if necessary
Correction measured variable Signal exceeded/drops below value	temp. input ↑↓	٣			yes	Pt100-signal >138.5 Ω Signal <3.0 ±0.2 mA or >23 ±0.2 mA Value last valid is used	Check probe, transducer and cable connection
Feed forward control Signal drops below value multiplicative additive Signal exceeded	feedfwd. < 4 mA	mm	Stop		Yes Yes	Signal <3.8 ±0.2 mA or >23 ±0.2 mA Value last valid is used	Check probe, transducer and cable connection
Limit transgression after checkout time limit value	H ₂ O ₂ limit 1 H ₂ O ₂ limit 2	\mathcal{T}			No	Function defeatable	Define cause, reset values if necessary
Control "off"	,	Mί	Stop or Basic load	Stop	Yes Yes		
Servomotor Position not reached	Servomotor defective	\sim			Yes	Servomotor closes	Check servomotor
Electronics error	System error	603	Stop	Stop	Yes	Elektronic data defective	Call in service

Fault / Remarks / Troubleshooting

Operation	Note text	Symbol	Effect	ČŤ	Alarm with ack-	Remarks	Remedy
,			on metering on control		nowledgement		
Pause contact	Pause	ε0	Stop	Stop	No/Yes*	No further foult about	I
	Pause/Hold	Μ		PI-part		IND INI NIEL TANIF CHECK	
		1		frozen			
Stop button	Stop	٤٥	Stop	Stop	No	Relay drops out	-
During calibration probe			Basic load	Stop in	No	No error processing of	ı
			+ Feed	complete		measured variable	
			forward	operating			
	2						
Probe slope too low Probe slope too high	Slope low Slope high	٤	Basic load	Stop	No	25% > probe of slope > 300% norm slope	Check probe, replace if necessary
H ₂ O ₂ -value <2 % measuring range	H_2O_2 too low					< 2 % from meas. range	
Zero point	Zero point low Zero point high	Μ	Basic load	Stop	No	Signal < 3 mA Signal > 5 mA	Check probe/cable Repeat calibration
							2-2
During servomotor setting Position feed back wrong	Direction check					Without correct	Check connection of relay,
Lower position >30 % range	Final value big					valid values are still used	Adjust the operation region of the servomotor correctly
*donordont on whathar "Alarm On" or "Alarm Off" is not in "Conord offings"	Norm Offin in oat in "Co	nord ootti	200				